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► To cite this version:

Alfred Galichon, Nassif Ghoussoub. Variational representations for N-cyclically monotone vector fields. Pacific Journal of Mathematics, 2014, 269 (2), pp.323 - 340. 10.2140/pjm.2014.269.323. hal-03460569

HAL Id: hal-03460569 https://sciencespo.hal.science/hal-03460569

Submitted on 1 Dec 2021

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Pacific Journal of Mathematics

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Volume 269 No. 2

June 2014

VARIATIONAL REPRESENTATIONS FOR N-CYCLICALLY MONOTONE VECTOR FIELDS

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Given a convex bounded domain Ω in \mathbb{R}^d and an integer $N \ge 2$, we associate to any *jointly N-monotone* (N-1)-tuplet $(u_1, u_2, \ldots, u_{N-1})$ of vector fields from Ω into \mathbb{R}^d a Hamiltonian H on $\mathbb{R}^d \times \mathbb{R}^d \times \cdots \times \mathbb{R}^d$ that is concave in the first variable, jointly convex in the last N-1 variables, and such that

$$(u_1(x), u_2(x), \ldots, u_{N-1}(x)) = \nabla_{2,\ldots,N} H(x, x, \ldots, x)$$

for almost all $x \in \Omega$. Moreover, *H* is *N*-antisymmetric in a sense made precise later, and also *N*-sub-antisymmetric in the sense that for all $X \in \Omega^N$ the sum $\sum_{i=0}^{N-1} H(\sigma^i(X)) \leq 0$ is nonpositive, σ being the permutation that shifts the coordinates of *X* leftward one slot and places the first coordinate last. This result can be seen as an extension of a theorem of E. Krauss, which associates to any monotone operator a concave-convex antisymmetric saddle function. We also give various variational characterizations of vector fields that are almost everywhere *N*-monotone, showing that they are dual to the class of measure-preserving *N*-involutions on Ω .

1. Introduction

Given a domain Ω in \mathbb{R}^d , recall that a single-valued map u from Ω to \mathbb{R}^d is said to be *N*-cyclically monotone if for every cycle $x_1, \ldots, x_N, x_{N+1} = x_1$ of points in Ω , one has

(1)
$$\sum_{i=1}^{N} \langle u(x_i), x_i - x_{i+1} \rangle \ge 0.$$

A classical theorem of Rockafellar [Phelps 1993] states that a map u from Ω to \mathbb{R}^d

Galichon's research has received funding from the European Research Council under the European Union's Seventh Framework Programme (FP7/2007–2013)/ ERC grant agreement n° 313699. Support from FiME, Laboratoire de Finance des Marchés de l'Énergie (http://www.fime-lab.org) is gratefully acknowledged. Ghoussoub is partially supported by a grant from the Natural Sciences and Engineering Research Council of Canada.

MSC2010: 49J40.

Keywords: N-cyclically monotone vector fields, Krauss theorem.

is *N*-cyclically monotone for every $N \ge 2$ if and only if

(2)
$$u(x) \in \partial \phi(x)$$
 for all $x \in \Omega$,

where $\phi : \mathbb{R}^d \to \mathbb{R}$ is a convex function. On the other hand, a result of E. Krauss [1985] yields that *u* is a monotone map, i.e., a 2-cyclically monotone map, if and only if

(3)
$$u(x) \in \partial_2 H(x, x)$$
 for all $x \in \Omega$,

where *H* is a concave-convex antisymmetric Hamiltonian on $\mathbb{R}^d \times \mathbb{R}^d$, and $\partial_2 H$ is the subdifferential of *H* as a convex function in the second variable.

In this paper, we extend the result of Krauss to the class of N-cyclically monotone vector fields, where $N \ge 3$. We shall give a representation for a family of N-1 vector fields, which may or may not be individually N-cyclically monotone. Here is the needed concept.

Definition 1. Let u_1, \ldots, u_{N-1} be bounded vector fields from a domain $\Omega \subset \mathbb{R}^d$ into \mathbb{R}^d . We shall say that the (N-1)-tuple $(u_1, u_2, \ldots, u_{N-1})$ is *jointly N-monotone* if for every cycle x_1, \ldots, x_{2N-1} of points in Ω such that $x_{N+i} = x_i$ for $1 \le i \le N-1$, one has

(4)
$$\sum_{i=1}^{N} \sum_{\ell=1}^{N-1} \langle u_l(x_i), x_i - x_{l+i} \rangle \ge 0.$$

Examples of jointly N-monotone families of vector fields:

- It is clear that (u, 0, 0, ..., 0) is jointly *N*-monotone if and only if *u* is *N*-monotone.
- More generally, if each u_{ℓ} is *N*-monotone, then the family $(u_1, u_2, \ldots, u_{N-1})$ is jointly *N*-monotone. Actually, one only needs that for $1 \le \ell \le N 1$, the vector field u_{ℓ} be (N, ℓ) -monotone in the following sense: for every cycle $x_1, \ldots, x_{N+\ell}$ of points in Ω such that $x_{N+i} = x_i$ for $1 \le i \le \ell$, we have

(5)
$$\sum_{i=1}^{N} \langle u_{\ell}(x_i), x_i - x_{\ell+i} \rangle \ge 0.$$

This notion is sometimes weaker than N-monotonicity since if ℓ divides N, then it suffices for u to be N/ℓ -monotone in order to be an (N, ℓ) -monotone vector field. For example, if u_1 and u_3 are 4-monotone operators and u_2 is 2-monotone, then the triplet (u_1, u_2, u_3) is jointly 4-monotone.

• Another example is if (u_1, u_2, u_3) are vector fields such that u_2 is 2-monotone and

$$\langle u_1(x) - u_3(y), x - y \rangle \ge 0$$
 for every $x, y \in \mathbb{R}^d$.

In this case, the triplet (u_1, u_2, u_3) is jointly 4-monotone. In particular, if u_1 and u_2 are both 2-monotone, then the triplet (u_1, u_2, u_1) is jointly 4-monotone.

• More generally, it is easy to show that (u, u, ..., u) is jointly *N*-monotone if and only if *u* is 2-cyclically monotone.

We shall always denote by σ the cyclic permutation on $\mathbb{R}^d \times \cdots \times \mathbb{R}^d$ defined by

$$\sigma(x_1, x_2, \ldots, x_{N-1}, x_N) = (x_2, x_3, \ldots, x_N, x_1).$$

We let

(6)
$$\mathscr{H}_N(\Omega) = \left\{ H \in C(\Omega^N) : \sum_{i=0}^{N-1} H(\sigma^i(x_1, \dots, x_N)) = 0 \right\}$$

be the family of continuous Hamiltonians on Ω^N that are *N*-antisymmetric, i.e., satisfy the condition to the right of the colon in (6). We say that *H* is *N*-sub-antisymmetric on Ω if

(7)
$$\sum_{i=0}^{N-1} H(\sigma^i(x_1,\ldots,x_N)) \le 0 \quad \text{on } \Omega^N.$$

We shall also say that a function F of two variables is *N*-cyclically sub-antisymmetric on Ω if

(8)
$$F(x, x) = 0 \text{ and}$$
$$\sum_{i=1}^{N} F(x_i, x_{i+1}) \le 0 \text{ for all cyclic families } x_1, \dots, x_N, x_{N+1} = x_1 \text{ in } \Omega.$$

Note that if a function $H(x_1, ..., x_N)$ *N*-sub-antisymmetric and if it only depends on the first two variables, then the function $F(x_1, x_2) := H(x_1, x_2, ..., x_N)$ is *N*-cyclically sub-antisymmetric.

We associate to any function H on Ω^N the functional given by on $\Omega \times (\mathbb{R}^d)^{N-1}$

(9)
$$L_H(x, p_1, \dots, p_{N-1}) = \sup \left\{ \sum_{i=1}^{N-1} \langle p_i, y_i \rangle - H(x, y_1, \dots, y_{N-1}) : y_i \in \Omega \right\}.$$

Note that if Ω is convex and if H is convex in the last N-1 variables, then L_H is nothing but the Legendre transform of \tilde{H} with respect to the last N-1 variables, where \tilde{H} is the extension of H over $(\mathbb{R}^d)^N$, defined by $\tilde{H} = H$ on Ω^N and $\tilde{H} = +\infty$ outside Ω^N . Since $H(x, \ldots, x) = 0$ for any $H \in \mathcal{H}_N(\Omega)$, we have, for any such H,

(10)
$$L_H(x, p_1, \dots, p_{N-1}) \ge \sum_{i=1}^{N-1} \langle x, p_i \rangle,$$

for $x \in \Omega$ and $p_1, \ldots, p_{N-1} \in \mathbb{R}^d$. To formulate variational principles for such

vector fields, we shall consider the class of σ -invariant probability measures on Ω^N , which are those $\pi \in \mathcal{P}(\Omega^N)$ such that for all $h \in L^1(\Omega^N, d\pi)$, we have

(11)
$$\int_{\Omega^N} h(x_1, \dots, x_N) d\pi = \int_{\Omega^N} h(\sigma(x_1, \dots, x_N)) d\pi$$

We set

(12)
$$\mathscr{P}_{\text{sym}}(\Omega^N) = \{ \pi \in \mathscr{P}(\Omega^N) : \pi \ \sigma \text{-invariant probability on } \Omega^N \}.$$

For a given probability measure μ on Ω , we also consider the class

(13)
$$\mathscr{P}^{\mu}_{\rm sym}(\Omega^N) = \{\pi \in \mathscr{P}_{\rm sym}(\Omega^N) : {\rm proj}_1\pi = \mu\},$$

i.e., the set of all $\pi \in \mathcal{P}_{sym}(\Omega^N)$ with a given first marginal μ , meaning that

(14)
$$\int_{\Omega^N} f(x_1) d\pi(x_1, \dots, x_N) = \int_{\Omega} f(x_1) d\mu(x_1) \text{ for every } f \in L^1(\Omega, \mu).$$

Now consider the set $\mathscr{G}(\Omega, \mu)$ of μ -measure-preserving transformations on Ω , which can be identified with a closed subset of the sphere of $L^2(\Omega, \mathbb{R}^d)$. We shall also consider the subset of $\mathscr{G}(\Omega, \mu)$ consisting of *N*-involutions, that is,

$$\mathcal{G}_N(\Omega, \mu) = \{ S \in \mathcal{G}(\Omega, \mu) : S^N = I \ \mu\text{-a.e.} \}.$$

2. Monotone vector fields and N-antisymmetric Hamiltonians

In this section, we establish the following extension of a theorem of Krauss.

Theorem 2. Let $N \ge 2$ be an integer, and let u_1, \ldots, u_{N-1} be bounded vector fields from a convex domain $\Omega \subset \mathbb{R}^d$ into \mathbb{R}^d .

1) If the (N-1)-tuple (u_1, \ldots, u_{N-1}) is jointly N-monotone, then there exists an N-sub-antisymmetric Hamiltonian H that is zero on the diagonal of Ω^N , concave in the first variable, convex in the other N-1 variables, and such that

(15)
$$(u_1(x), \dots, u_{N-1}(x)) = \nabla_{2,\dots,N} H(x, x, \dots, x)$$
 for a.e. $x \in \Omega$.

Moreover, H is N-antisymmetric in the sense that

(16)
$$H(x_1, x_2, \dots, x_N) + H_{2,\dots,N}(x_1, x_2, \dots, x_N) = 0,$$

where $H_{2,...,N}$ is the concavification of the function $K(\mathbf{x}) = \sum_{i=1}^{N-1} H(\sigma^i(\mathbf{x}))$ with respect to the last N-1 variables.

Furthermore, there exists a continuous N-antisymmetric Hamiltonian \overline{H} on Ω^N , such that

(17)
$$L_{\overline{H}}(x, u_1(x), u_2(x), \dots, u_{N-1}(x)) = \sum_{i=1}^{N-1} \langle u_i(x), x \rangle$$
 for all $x \in \Omega$.

2) Conversely, if (u_1, \ldots, u_{N-1}) satisfies (15) for some N-sub-antisymmetric Hamiltonian H that is zero on the diagonal of Ω^N , concave in the first variable, and convex in the other variables, then the (N-1)-tuple (u_1, \ldots, u_{N-1}) is jointly N-monotone on Ω .

Remark 3. In the case N = 2, $K(\mathbf{x}) = H(x_2, x_1)$ is concave with respect to x_2 , hence $H_2(x_1, x_2) = H(x_2, x_1)$, and (16) becomes

$$H(x_1, x_2) + H(x_2, x_1) = 0;$$

thus *H* is antisymmetric, recovering well-known results [Krauss 1985; Ghoussoub 2009; Ghoussoub and Moameni 2013a; Millien 2011].

Lemma 4. Assume the (N-1)-tuple of bounded vector fields (u_1, \ldots, u_{N-1}) on Ω is jointly N-monotone. Define

$$f(x_1, \ldots, x_N) := \sum_{l=1}^{N-1} \langle u_l(x_1), x_1 - x_{l+1} \rangle$$

and let \tilde{f} be the convexification of f with respect to the first variable, given by

- (18) $\tilde{f}(x_1, x_2, \dots, x_N)$ = $\inf \left\{ \sum_{k=1}^n \lambda_k f(x_1^k, x_2, \dots, x_N) : n \in \mathbb{N}, \ \lambda_k \ge 0, \ \sum_{k=1}^n \lambda_k = 1, \ \sum_{k=1}^n \lambda_k x_1^k = x_1 \right\}.$
 - 1) We have $f \geq \tilde{f}$ on Ω^N .
 - 2) \tilde{f} is convex in the first variable and concave with respect to the other variables.
 - 3) $\tilde{f}(x, x, \dots, x) = 0$ for each $x \in \Omega$.
 - 4) \tilde{f} satisfies

(19)
$$\sum_{i=0}^{N-1} \tilde{f}(\sigma^i(x_1,\ldots,x_N)) \ge 0 \quad on \ \Omega^N.$$

Proof. Since the (N-1)-tuple (u_1, \ldots, u_{N-1}) is jointly N-monotone, it is easy to see that the function

$$f(x_1, \ldots, x_N) := \sum_{l=1}^{N-1} \langle u_l(x_1), x_1 - x_{l+1} \rangle$$

is linear in the last N-1 variables, that f(x, x, ..., x) = 0, and that

(20)
$$\sum_{i=0}^{N-1} f(\sigma^i(x_1,\ldots,x_N)) \ge 0 \quad \text{on } \Omega^N.$$

It is also clear that $f \ge \tilde{f}$, that \tilde{f} is convex with respect to the first variable x_1 ,

and that it is concave with respect to the other variables x_2, \ldots, x_N , since f itself is concave (actually linear) with respect to x_2, \ldots, x_N . We now show that \tilde{f} satisfies (19).

For that, we fix x_1, x_2, \ldots, x_N in Ω and consider $(x_1^k)_{k=1}^n$ in Ω , and $(\lambda_k)_k$ in \mathbb{R} such that $\lambda_k \ge 0$ such that $\sum_{k=1}^n \lambda_k = 1$ and $\sum_{k=1}^n \lambda_k x_1^k = x_1$. For each k, we have

$$f(x_1^k, x_2, \ldots, x_N) + f(x_2, \ldots, x_N, x_1^k) + \cdots + f(x_N, x_1^k, x_2, \ldots, x_{N-1}) \ge 0.$$

Multiplying by λ_k , summing over k, and using that f is linear in the last N-1 variables, we have

$$\sum_{k=1}^{n} \lambda_k f(x_1^k, x_2, \dots, x_N) + f(x_2, \dots, x_N, x_1) + \dots + f(x_N, x_1, x_2, \dots, x_{N-1}) \ge 0.$$

By taking the infimum, we obtain

$$\tilde{f}(x_1, x_2, \dots, x_N) + \sum_{i=1}^{N-1} f(\sigma^i(x_1, x_2, \dots, x_N)) \ge 0.$$

Let now $n \in \mathbb{N}$, $\lambda_k \ge 0$, $x_N^k \in \Omega$ be such that $\sum_{k=1}^n \lambda_k = 1$ and $\sum_{k=1}^n \lambda_k x_2^k = x_2$. For every $1 \le k \le n$, we have

$$\tilde{f}(x_1, x_2^k, x_3, \dots, x_N) + f(x_2^k, x_3, \dots, x_1) + \dots + f(x_N, x_1, x_2^k, x_3, \dots, x_{N-1}) \ge 0.$$

Multiplying by λ_k , summing over k and using that \tilde{f} is convex in the first variable and f is linear in the last N-1 variables, we obtain

$$\tilde{f}(x_1, x_2, x_3, \dots, x_N) + \sum_{k=1}^n \lambda_k f(x_2^k, x_3, \dots, x_1) + \dots + f(x_N, x_1, x_2, x_3, \dots, x_{N-1})$$

$$\geq \sum_{k=1}^n \lambda_k \tilde{f}(x_1, x_2^k, x_3, \dots, x_N) + \sum_{k=1}^n \lambda_k f(x_2^k, x_3, \dots, x_1) + \dots + \sum_{k=1}^n \lambda_k f(x_N, x_1, x_2^k, x_3, \dots, x_{N-1})$$

$$\geq 0.$$

By taking the infimum over all possible such choices, we get

$$\tilde{f}(x_1, x_2, x_3, \dots, x_N) + \tilde{f}(x_2, x_3, \dots, x_1) + \dots + f(x_N, x_1, x_2, x_3, \dots, x_{N-1}) \ge 0$$

By repeating this procedure with x_3, \ldots, x_{N-1} , we get

$$\sum_{i=0}^{N-2} \tilde{f}(\sigma^{i}(x_{1}, x_{2}, \dots, x_{N})) + f(x_{N}, x_{1}, x_{2}, x_{3}, \dots, x_{N-1}) \ge 0$$

Finally, since

$$f(x_N, x_1, x_2, x_3, \dots, x_{N-1}) \ge -\sum_{i=0}^{N-2} \tilde{f}(\sigma^i(x_1, x_2, \dots, x_N))$$

and since \tilde{f} is concave in the last N-1 variables, the function

$$x_N \rightarrow -\sum_{i=0}^{N-2} \tilde{f}(\sigma^i(x_1, x_2, \dots, x_N))$$

for fixed $x_1, x_2, \ldots, x_{N-1}$ is a convex minorant of $x_N \to f(x_N, x_1, x_2, \ldots, x_{N-1})$. It follows that

$$f(x_N, x_1, x_2, x_3, \dots, x_{N-1}) \ge \tilde{f}(x_N, x_1, x_2, x_3, \dots, x_{N-1})$$
$$\ge -\sum_{i=0}^{N-2} \tilde{f}(\sigma^i(x_1, x_2, \dots, x_N)),$$

which yields $\sum_{i=0}^{N-1} \tilde{f}(\sigma^i(x_1, x_2, \dots, x_N)) \ge 0$. This implies that $\tilde{f}(x, x, \dots, x) \ge 0$ for $x \in \Omega$.

On the other hand, since $\tilde{f}(x, x, ..., x) \leq f(x, x, ..., x) = 0$, we get that $\tilde{f}(x, x, ..., x) = 0$ for all $x \in \Omega$.

Proof of Theorem 2. Assume the (N-1)-tuple of vector fields (u_1, \ldots, u_{N-1}) is jointly *N*-monotone on Ω , and consider the function

$$f(x_1, \ldots, x_N) := \sum_{l=1}^{N-1} \langle u_l(x_1), x_1 - x_{l+1} \rangle$$

as well as its convexification with respect to the first variable $\tilde{f}(x_1, \ldots, x_N)$.

By Lemma 4, the function $\psi(x_1, \ldots, x_N) := -\tilde{f}(x_1, \ldots, x_N)$ satisfies the following properties:

- (i) $x_1 \rightarrow \psi(x_1, \ldots, x_N)$ is concave.
- (ii) $(x_2, x_3, \ldots, x_N) \rightarrow \psi(x_1, \ldots, x_N)$ is convex.

(iii)
$$\psi(x_1, \ldots, x_N) \ge -f(x_1, \ldots, x_N) = \sum_{l=1}^{N-1} \langle u_l(x_1), x_{l+1} - x_1 \rangle.$$

(iv) ψ is *N*-sub-antisymmetric.

Now consider the family $\overline{\mathcal{H}}$ of functions $H: \Omega^N \to \mathbb{R}$ such that

- 1) $H(x_1, x_2, ..., x_N) \ge \sum_{l=1}^{N-1} \langle u_l(x_1), x_{l+1} x_1 \rangle$ for every *N*-tuple $(x_1, ..., x_N)$ in Ω^N ,
- 2) *H* is concave in the first variable,
- 3) *H* is jointly convex in the last N-1 variables,

- 4) *H* is *N*-sub-antisymmetric,
- 5) *H* is zero on the diagonal of Ω^N .

Note that $\overline{\mathcal{H}} \neq \emptyset$ since ψ belongs to $\overline{\mathcal{H}}$. Note that any *H* satisfying conditions 1 and 4 automatically satisfies 5. Indeed, by *N*-sub-antisymmetry, for all $\mathbf{x} = (x_1, \ldots, x_N) \in \Omega^N$ we have

(21)
$$H(\mathbf{x}) \le -\sum_{i=1}^{N-1} H(\sigma^{i}(\mathbf{x})) \le -\sum_{i=1}^{N-1} \psi(\sigma^{i}(\mathbf{x})).$$

This also yields that

(22)
$$\sum_{\ell=1}^{N-1} \langle u_{\ell}(x_1), x_{\ell+1} - x_1 \rangle \le H(\mathbf{x}) \le -\sum_{i=2}^{N} \sum_{\ell=1}^{N-1} \langle u_{\ell}(x_i), x_i - x_{i+\ell} \rangle,$$

where we denote $x_{i+N} := x_i$ for $i = 1, ..., \ell$. This yields that H(x, x, ..., x) = 0 for any $x \in \Omega$.

It is also easy to see that every directed family $(H_i)_i$ in $\overline{\mathcal{H}}$ has a supremum $H_{\infty} \in \overline{\mathcal{H}}$, meaning that $\overline{\mathcal{H}}$ is a Zorn family, and therefore has a maximal element H.

Now consider the function

$$\overline{H}(\boldsymbol{x}) = \frac{1}{N} \left((N-1)H(\boldsymbol{x}) - \sum_{i=1}^{N-1} H(\sigma^{i}(\boldsymbol{x})) \right).$$

- (i) \overline{H} is *N*-antisymmetric, since $\overline{H}(\mathbf{x}) = \frac{1}{N} \sum_{i=1}^{N-1} [H(\mathbf{x}) H(\sigma^i(\mathbf{x}))]$, and each summand is *N*-antisymmetric.
- (ii) $\overline{H} \ge H$ on Ω^N , since $N[\overline{H}(\mathbf{x}) H(\mathbf{x})] = -\sum_{i=0}^{N-1} H(\sigma^i(\mathbf{x})) \ge 0$ (because H itself is N-sub-antisymmetric).

The maximality of H would have implied that $H = \overline{H}$ is N-antisymmetric if only \overline{H} was jointly convex in the last N-1 variables, but since this is not necessarily the case, we consider for $\mathbf{x} = (x_1, x_2, \dots, x_N)$ the function

$$K(x_1, x_2, ..., x_N) = K(\mathbf{x}) := -\sum_{i=1}^{N-1} H(\sigma^i(\mathbf{x}))$$

which is already concave in the first variable x_1 . Its convexification in the last N-1 variables, that is,

$$K^{2,\dots,N}(\mathbf{x}) = \inf \left\{ \sum_{i=1}^{n} \lambda_i K(x_1, x_2^i, \dots, x_N^i) : \lambda_i \ge 0, \sum_{i=1}^{n} \lambda_i (x_2^i, \dots, x_N^i, 1) = (x_2, \dots, x_N, 1) \right\},\$$

is still concave in the first variable, but is now convex in the last N-1 variables. Moreover,

(23)
$$H \le K^{2,...,N} \le K = -\sum_{i=1}^{N-1} H \circ \sigma^{i}.$$

Indeed, $K^{2,...,N} \leq K$ from the definition of $K^{2,...,N}$, while $H \leq K^{2,...,N}$ because $H \leq K$ and H is already convex in the last N-1 variables. It follows that

$$H \le \frac{(N-1)H + K^{2,\dots,N}}{N} \le \frac{(N-1)H + K}{N} = \frac{1}{N} \left((N-1)H - \sum_{i=1}^{N-1} H \circ \sigma^i \right) = \overline{H}.$$

The function $H' = ((N-1)H + K^{2,...,N})/N$ belongs to the family $\overline{\mathcal{H}}$ and therefore H = H' by the maximality of H.

This finally yields that *H* is *N*-sub-antisymmetric, that H(x, ..., x) = 0 for all $x \in \Omega$ and that

$$H(\mathbf{x}) + H_{2,\dots,N}(\mathbf{x}) = 0$$
 for every $\mathbf{x} \in \Omega^N$,

where $H_{2,...,N} = -K^{2,...,N}$, which for a fixed x_1 is nothing but the concavification of $(x_2,...,x_N) \rightarrow \sum_{i=1}^{N-1} H(\sigma^i(x_1,x_2,...,x_N))$.

Note now that since for any x_1, \ldots, x_N in Ω

(24)
$$H(x_1, x_2, \dots, x_N) \ge \sum_{\ell=1}^{N-1} \langle u_\ell(x_1), x_{\ell+1} - x_1 \rangle,$$

and

(25)
$$H(x_1, x_1, \dots, x_1) = 0,$$

we have

(26)
$$H(x_1, x_2, \dots, x_N) - H(x_1, \dots, x_1) \ge \sum_{\ell=1}^{N-1} \langle u_\ell(x_1), x_{\ell+1} - x_1 \rangle$$

Since *H* is convex in the last N-1 variables, this means that for all $x \in \Omega$, we have

(27)
$$(u_1(x), u_2(x), \dots, u_{N-1}(x)) \in \partial_{2,\dots,N} H(x, x, \dots, x),$$

as claimed in (15). This also yields

$$L_H(x, u_1(x), \dots, u_{N-1}(x)) + H(x, x, \dots, x) = \sum_{\ell=1}^{N-1} \langle u_\ell(x), x \rangle \quad \text{for all } x \in \Omega.$$

In other words, $L_H(x, u_1(x), \dots, u_{N-1}(x)) = \sum_{\ell=1}^{N-1} \langle u_\ell(x), x \rangle$ for all $x \in \Omega$. As above, consider

$$\overline{H}(\boldsymbol{x}) = \frac{1}{N} \bigg((N-1)H(\boldsymbol{x}) - \sum_{i=1}^{N-1} H(\sigma^{i}(\boldsymbol{x})) \bigg).$$

We have $\overline{H} \in \overline{\mathcal{H}}_N(\Omega)$ and $\overline{H} \ge H$, and therefore $L_{\overline{H}} \le L_H$. On the other hand, for all $x \in \Omega$ we have

$$L_{\overline{H}}(x, u_1(x), \dots, u_{N-1}(x)) = L_{\overline{H}}(x, u_1(x), \dots, u_{N-1}(x)) + \overline{H}(x, x, \dots, x)$$
$$\geq \sum_{\ell=1}^{N-1} \langle u_\ell(x), x \rangle.$$

To prove (17), we use the appendix in [Ghoussoub and Moameni 2013b] to deduce that for i = 2, ..., N, the gradients $\nabla_i H(x, x, ..., x)$ actually exist for a.e. x in Ω .

The converse is straightforward since if (27) holds, then (26) does, and since we also have (25), then the property that (u_1, \ldots, u_{N-1}) is jointly *N*-monotone follows from (24) and the sub-antisymmetry of *H*.

In the case of a single *N*-monotone vector field, we can obviously apply the above theorem to the (N-1)-tuple (u, 0, ..., 0), which is then *N*-monotone, to find an *N*-sub-antisymmetric Hamiltonian *H*, which is concave in the first variable and convex in the last N-1 variables such that

(28)
$$(-u(x), u(x), 0, \dots, 0) = \nabla H(x, x, \dots, x)$$
 for a.e. $x \in \Omega$.

However, in this case we can restrict ourselves to *N*-cyclically sub-antisymmetric functions of two variables and establish the following extension of the theorem of Krauss.

Theorem 5. If u is N-cyclically monotone on Ω , then there exists a concave-convex function of two variables F that is N-cyclically sub-antisymmetric and zero on the diagonal, such that

(29)
$$(-u(x), u(x)) \in \partial F(x, x) \text{ for all } x \in \Omega,$$

where ∂H is the subdifferential of H as a concave-convex function [Rockafellar 1970]. Moreover,

(30)
$$u(x) = \nabla_2 F(x, x) \quad \text{for a.e. } x \in \Omega.$$

Proof. Let $f(x, y) = \langle u(x), x - y \rangle$ and let $f^{1}(x, y)$ be its convexification in x for fixed y, that is,

(31)
$$f^{1}(x, y) = \inf \left\{ \sum_{k=1}^{n} \lambda_{k} f(x_{k}, y) : \lambda_{k} \ge 0, \sum_{k=1}^{n} \lambda_{k} = 1, \sum_{k=1}^{n} \lambda_{k} x_{k} = x \right\}.$$

Since f(x, x) = 0, f is linear in y, and $\sum_{i=1}^{\infty} f(x_i, x_{i+1}) \ge 0$ for any cyclic family

 $x_1, \ldots, x_N, x_{N+1} = x_1$ in Ω , it is easy to show that $f \ge f^1$ on Ω , f^1 is convex in the first variable and concave with respect to the second, $f^1(x, x) = 0$ for each $x \in \Omega$, and that f^1 is *N*-cyclically supersymmetric in the sense that for any cyclic family $x_1, \ldots, x_N, x_{N+1} = x_1$ in Ω , we have $\sum_{i=1}^N f^1(x_i, x_{i+1}) \ge 0$.

Now consider $F(x, y) = -f^1(x, y)$ and note that $x \to F(x, y)$ is concave, $y \to F(x, y)$ is convex, $F(x, y) \ge -f(x, y) = \langle u(x), y - x \rangle$ and F is N-cyclically sub-antisymmetric. By the antisymmetry, we have

(32)
$$\langle u(x_1), x_2 - x_1 \rangle \le F(x_1, x_2) \le \langle u(x_2), x_2 - x_1 \rangle,$$

which yields that $(-u(x), u(x)) \in \partial F(x, x)$ for all $x \in \Omega$.

Since *F* is antisymmetric and concave-convex, the possibly multivalued map $x \rightarrow \partial_2 F(x, x)$ is monotone on Ω , and therefore single-valued and differentiable almost everywhere [Phelps 1993]. This completes the proof.

Remark 6. We cannot expect to have a function F such that $\sum_{i=1}^{N} F(x_i, x_{i+1}) = 0$ for all cyclic families $x_1, \ldots, x_N, x_{N+1} = x_1$ in Ω . Actually, we believe that the only function satisfying such an *N*-antisymmetry for $N \ge 3$ must be of the form F(x, y) = f(x) - f(y). This is why one needs to consider functions of *N* variables in order to get *N*-antisymmetry. In other words, the function defined by

(33)
$$H(x_1, x_2, \dots, x_N) := \frac{1}{N} \left((N-1)F(x_1, x_2) - \sum_{i=2}^{N-1} F(x_i, x_{i+1}) \right)$$

is *N*-antisymmetric in the sense of (6) and $H(x_1, x_2, ..., x_N) \ge F(x_1, x_2)$ for all $(x_1, x_2, ..., x_N)$ in Ω^N .

3. Variational characterization of monotone vector fields

In order to simplify the exposition, we shall always assume in the sequel that $d\mu$ is Lebesgue measure dx normalized to be a probability on Ω . We shall also assume that Ω is convex and that its boundary has measure zero.

Theorem 7. Let $u_1, \ldots, u_{N-1} : \Omega \to \mathbb{R}^d$ be bounded measurable vector fields. The following properties are then equivalent:

- The (N-1)-tuple (u₁,..., u_{N-1}) is jointly N-monotone a.e., that is, there exists a measure-zero set Ω₀ such that (u₁,..., u_{N-1}) is jointly N-monotone on Ω \ Ω₀.
- 2) The infimum of the Monge-Kantorovich problem

(34)
$$\inf\left\{\int_{\Omega^{N}}\sum_{\ell=1}^{N-1} \langle u_{\ell}(x_{1}), x_{1} - x_{\ell+1} \rangle \, d\pi(x_{1}, x_{2}, \dots, x_{N})) : \pi \in \mathcal{P}_{\text{sym}}^{\mu}(\Omega^{N})\right\}$$

is equal to zero, and is therefore attained by the push-forward of μ by the map $x \rightarrow (x, x, \dots, x)$.

3) (u_1, \ldots, u_{N-1}) is in the polar of $\mathcal{G}_N(\Omega, \mu)$ in the following sense:

(35)
$$\inf\left\{\int_{\Omega}\sum_{\ell=1}^{N-1} \langle u_{\ell}(x), x - S^{\ell}x \rangle \, d\mu : S \in \mathcal{G}_{N}(\Omega, \mu)\right\} = 0.$$

4) *The following holds*:

(36)
$$\inf\left\{\int_{\Omega}\sum_{\ell=1}^{N-1}|u_{\ell}(x)-S^{\ell}x|^{2}\,d\mu:S\in\mathcal{G}_{N}(\Omega,\mu)\right\}=\sum_{\ell=1}^{N-1}\int_{\Omega}|u_{\ell}(x)-x|^{2}\,d\mu.$$

5) There exists an N-sub-antisymmetric Hamiltonian H which is concave in the first variable, convex in the last N−1 variables, and vanishing on the diagonal such that

(37)
$$(u_1(x), \dots, u_{N-1}(x)) = \nabla_{2,\dots,N} H(x, x, \dots, x)$$
 for a.e. $x \in \Omega$.

Moreover, H is N-symmetric in the sense of (16).

6) The following duality holds:

$$\inf\left\{\int_{\Omega} L_{H}(x, u_{1}(x), \dots, u_{N-1}(x)) d\mu : H \in \mathcal{H}_{N}(\Omega)\right\}$$
$$= \sup\left\{\int_{\Omega} \sum_{\ell=1}^{N-1} \langle u_{\ell}(x), S^{\ell}x \rangle d\mu : S \in \mathcal{G}_{N}(\Omega, \mu)\right\}$$

and the latter is attained at the identity map.

We start with the following lemma, which identifies those probabilities in $\mathcal{P}^{\mu}_{sym}(\Omega^N)$ that are carried by graphs of functions from Ω to Ω^N .

Lemma 8. Let $S : \Omega \to \Omega$ be a μ -measurable map. The following properties are equivalent:

- 1) The image of μ by the map $x \to (x, Sx, \dots, S^{N-1}x)$ belongs to $\mathcal{P}^{\mu}_{sym}(\Omega^N)$.
- 2) *S* is μ -measure-preserving and $S^N(x) = x \mu$ -a.e.
- 3) For any bounded Borel measurable N-antisymmetric H on Ω^N , we have $\int_{\Omega} H(x, Sx, \dots, S^{N-1}x) d\mu = 0.$

Proof. Clearly 1) implies 3), since $\int_{\Omega^N} H(\mathbf{x}) d\pi(\mathbf{x}) = 0$ for any *N*-antisymmetric Hamiltonian *H* and any $\pi \in \mathcal{P}_{\text{sym}}^{\mu}(\Omega^N)$.

That 2) implies 1) is also straightforward since if π is the push-forward of μ by a map of the form $x \to (x, Sx, \dots, S^{N-1}x)$, where S is a μ -measure-preserving S

with $S^N x = x \mu$ -a.e. on Ω , then for all $h \in L^1(\Omega^N, d\pi)$, we have

$$\int_{\Omega^N} h(x_1, \dots, x_N) d\pi = \int_{\Omega} h(x, Sx, \dots, S^{N-1}x) d\mu(x)$$
$$= \int_{\Omega} h(Sx, S^2x, \dots, S^{N-1}x, S^Nx) d\mu(x)$$
$$= \int_{\Omega} h(Sx, S^2x, \dots, S^{N-1}x, x) d\mu(x)$$
$$= \int_{\Omega^N} h(\sigma(x_1, \dots, x_N)) d\pi.$$

We now prove that 2) and 3) are equivalent. Assuming first that S is μ -measurepreserving such that $S^N = I \mu$ -a.e., then for every Borel bounded N-antisymmetric *H*, we have

$$\int_{\Omega} H(x, Sx, S^2x, \dots, S^{N-1}x) d\mu = \int_{\Omega} H(Sx, S^2x, \dots, S^{N-1}x, x) d\mu$$
$$= \dots = \int_{\Omega} H(S^{N-1}x, x, Sx, \dots, S^{N-2}x) d\mu.$$

Since *H* is *N*-antisymmetric, we can see that

$$H(x, Sx, \dots, S^{N-1}x) + H(Sx, S^2x, \dots, S^{N-1}x, x) + \dots + H(S^{N-1}x, x, Sx, \dots, S^{N-2}x) = 0.$$

It follows that $N \int_{\Omega} H(x, Sx, S^2x, \dots, S^{N-1}x) d\mu = 0$. For the reverse implication, assume $\int_{\Omega} H(x, Sx, S^2x, \dots, S^{N-1}x) d\mu = 0$ for every N-antisymmetric Hamiltonian H. By testing this identity with the Hamiltonians

$$H(x_1, x_2, \ldots, x_N) = f(x_1) - f(x_i),$$

where f is any continuous function on Ω , one gets that S is μ -measure-preserving. Now take the Hamiltonian

$$H(x_1, x_2, \dots, x_N) = |x_1 - Sx_N| - |Sx_1 - x_2| - |x_2 - Sx_1| + |Sx_2 - x_3|.$$

Note that $H \in \mathcal{H}_N(\Omega)$ since it is of the form

$$H(x_1, \ldots, x_N) = f(x_1, x_2, x_N) - f(x_2, x_3, x_1).$$

Now test the above identity with such an H to obtain

$$0 = \int_{\Omega} H(x, Sx, S^2x, \dots, S^{N-1}x) \, d\mu = \int_{\Omega} |x - SS^{N-1}x| \, d\mu.$$

It follows that $S^N = I \mu$ -a.e. on ω , and we are done.

Proof of Theorem 7. To show that 1) implies 2), it suffices to notice that if π is a σ -invariant probability measure on Ω^N such that $\text{proj}_1\pi = \mu$, then

$$\begin{split} \int_{\Omega^{N}} \sum_{\ell=1}^{N-1} \langle u_{\ell}(x_{1}), x_{1} - x_{\ell+1} \rangle \, d\pi(x_{1}, \dots, x_{N}) \\ &= \frac{1}{N} \sum_{i=1}^{N} \int_{\Omega^{N}} \sum_{\ell=1}^{N-1} \langle u_{\ell}(x_{i}), x_{i} - x_{i+\ell} \rangle \, d\pi(x_{1}, \dots, x_{N}) \\ &= \frac{1}{N} \int_{\Omega^{N}} \left(\sum_{i=1}^{N} \sum_{\ell=1}^{N-1} \langle u_{\ell}(x_{i}), x_{i} - x_{i+\ell} \rangle \right) d\pi(x_{1}, \dots, x_{N}) \\ &\geq 0, \end{split}$$

since (u_1, \ldots, u_{N-1}) is jointly *N*-monotone. On the other hand, if π is the σ -invariant measure obtained by taking the image of $\mu := dx$ by $x \to (x, \ldots, x)$, then

$$\int_{\Omega^N} \sum_{\ell=1}^{N-1} \langle u_\ell(x_1), x_1 - x_{\ell+1} \rangle \, d\pi(x_1, \dots, x_N) = 0.$$

To show that 2) implies 3), let *S* be a μ -measure-preserving transformation on Ω such that $S^N = I \mu$ -a.e. on Ω . Then the image π_S of μ by the map

$$x \to (x, Sx, S^2x, \dots, S^{N-1}x)$$

is σ -invariant, hence

$$\int_{\Omega^N} \sum_{\ell=1}^{N-1} \langle u_\ell(x_1), x_1 - x_{\ell+1} \rangle \, d\pi_S(x_1, \dots, x_N) = \int_{\Omega} \sum_{\ell=1}^{N-1} \langle u_\ell(x), x - S^\ell x \rangle \, d\mu \ge 0.$$

By taking S = I, we get that the infimum is necessarily zero.

The equivalence of 3) and 4) follows immediately from developing the square.

We now show that 3) implies 1). Take N points x_1, x_2, \ldots, x_N in Ω , and let R > 0 be such that $B(x_i, R) \subset \Omega$. Consider the transformation

$$S_R(x) = \begin{cases} x - x_1 + x_2 & \text{for } x \in B(x_1, R), \\ x - x_2 + x_3 & \text{for } x \in B(x_2, R), \\ \vdots \\ x - x_N + x_1 & \text{for } x \in B(x_N, R), \\ x & \text{otherwise.} \end{cases}$$

It is easy to see that S_R is a measure-preserving transformation and that $S_R^N = \text{Id.}$

We then have

c

$$0 \le \int_{\Omega} \sum_{\ell=1}^{N-1} \langle u_{\ell}(x), x - S_{R}^{\ell} x \rangle \, d\mu \le \sum_{i=1}^{N} \int_{B(x_{i},R)} \sum_{\ell=1}^{N-1} \langle u_{\ell}(x), x_{i} - x_{\ell+i} \rangle \, d\mu.$$

Letting $R \rightarrow 0$, we get from Lebesgue's density theorem that

$$\frac{1}{|B(x_i, R)|} \int_{B(x_i, R)} \langle u_{\ell}(x), x_i - x_{\ell+i} \rangle d\mu \to \langle u_{\ell}(x_i), x_i - x_{\ell+i} \rangle,$$

from which follows that (u_1, \ldots, u_{N-1}) are jointly N-monotone a.e. on Ω . The fact that 1) is equivalent to 5) follows immediately from Theorem 2.

To prove that 5) implies 6), note that for all $p_i \in \mathbb{R}^d$, $x \in \Omega$, $y_i \in \Omega$, i = $1, \ldots, N-1,$

$$L_H(x, p_1, \dots, p_{N-1}) + H(x, y_1, \dots, y_{N-1}) \ge \sum_{i=1}^{N-1} \langle p_i, y_i \rangle,$$

which yields that for any $S \in \mathcal{G}_N(\Omega, \mu)$,

$$\int_{\Omega} [L_H(x, u_1(x), \dots, u_{N-1}(x)) d\mu + H(x, Sx, \dots, S^{N-1}x)] d\mu$$
$$\geq \int_{\Omega} \sum_{\ell=1}^{N-1} \langle u_\ell(x), S^\ell x \rangle d\mu.$$

If $H \in \mathscr{H}_N(\Omega)$ and $S \in \mathscr{G}_N(\Omega, \mu)$, we then have $\int_{\Omega} H(x, Sx, \dots, S^{N-1}x) d\mu = 0$, and therefore

$$\int_{\Omega} L_H(x, u_1(x), \ldots, u_{N-1}(x)) d\mu \ge \int_{\Omega} \sum_{\ell=1}^{N-1} \langle u_\ell(x), S^\ell x \rangle d\mu.$$

If now H is the N-sub-antisymmetric Hamiltonian obtained by 5), which is concave in the first variable and convex in the last N-1 variables, then

$$L_H(x, u_1(x), \dots, u_{N-1}(x)) + H(x, x, \dots, x) = \sum_{\ell=1}^{N-1} \langle u_\ell(x), x \rangle \quad \text{for all } x \in \Omega \setminus \Omega_0,$$

and therefore $\int_\Omega L_H(x, u_1(x), \dots, u_{N-1}(x)) d\mu = \sum_{\ell=1}^{N-1} \int_\Omega \langle u_\ell(x), x \rangle d\mu.$
Now consider

Now consider

$$\overline{H}(\boldsymbol{x}) = \frac{1}{N} \bigg((N-1)H(\boldsymbol{x}) - \sum_{i=1}^{N-1} H(\sigma^{i}(\boldsymbol{x})) \bigg).$$

As before, we have $\overline{H} \in \mathcal{H}_N(\Omega)$ and $\overline{H} \ge H$. Since $L_{\overline{H}} \le L_H$, we have

$$\int_{\Omega} L_{\overline{H}}(x, u_1(x), \dots, u_{N-1}(x)) d\mu = \sum_{\ell=1}^{N-1} \int_{\Omega} \langle u_\ell(x), x \rangle d\mu$$

and 6) is proved.

Finally, note that 6) readily implies 3), which means that (u_1, \ldots, u_{N-1}) is then jointly *N*-monotone.

We now consider again the case of a single N-cyclically monotone vector field.

Corollary 9. Let $u : \Omega \to \mathbb{R}^d$ be a bounded measurable vector field. The following properties are then equivalent:

- 1) The vector field u is N-cyclically monotone a.e., that is, there exists a measurezero set Ω_0 such that u is N-cyclically monotone on $\Omega \setminus \Omega_0$.
- 2) The infimum of the Monge-Kantorovich problem

(38)
$$\inf\left\{\int_{\Omega^N} \langle u(x_1), x_1 - x_2 \rangle \, d\pi(\boldsymbol{x}) : \pi \in \mathcal{P}^{\mu}_{\text{sym}}(\Omega^N)\right\}$$

is equal to zero, and is therefore attained by the push-forward of μ by the map $x \rightarrow (x, x, \dots, x)$.

3) The vector field u is in the polar of $\mathcal{G}_N(\Omega, \mu)$, that is,

(39)
$$\inf\left\{\int_{\Omega} \langle u(x), x - Sx \rangle \, d\mu : S \in \mathcal{G}_N(\Omega, \mu)\right\} = 0.$$

4) The projection of u on $\mathcal{G}_N(\Omega, \mu)$ is the identity map, that is,

(40)
$$\inf\left\{\int_{\Omega}|u(x)-Sx|^2\,d\mu:S\in\mathcal{G}_N(\Omega,\mu)\right\}=\int_{\Omega}|u(x)-x|^2\,d\mu.$$

5) There exists an N-cyclically sub-antisymmetric function H of two variables, which is concave in the first variable, convex in the second variable, vanishing on the diagonal and such that

(41)
$$u(x) = \nabla_2 H(x, x) \quad \text{for a.e. } x \in \Omega.$$

6) The following duality holds:

$$\inf\left\{\int_{\Omega} L_{H}(x, u(x), 0, \dots, 0) \, d\mu : H \in \mathcal{H}_{N}(\Omega)\right\}$$
$$= \sup\left\{\int_{\Omega} \langle u(x), Sx \rangle \, d\mu : S \in \mathcal{G}_{N}(\Omega, \mu)\right\}$$

and the latter is attained at the identity map.

Proof. This is an immediate application of Theorem 7 applied to the (N-1)-tuplet vector fields (u, 0, ..., 0), which is clearly jointly *N*-monotone on $\Omega \setminus \Omega_0$, whenever *u* is *N*-monotone on $\Omega \setminus \Omega_0$.

Remark 10. The sets of μ -measure-preserving *N*-involutions $(\mathcal{G}_N(\Omega, \mu))_N$ do not form a nested family, that is, $\mathcal{G}_N(\Omega, \mu)$ is not necessarily included in $\mathcal{G}_M(\Omega, \mu)$, whenever $N \leq M$, unless of course *M* is a multiple of *N*. On the other hand, the above theorem shows that their polar sets, i.e.,

$$\mathcal{G}_N(\Omega,\mu)^0 = \left\{ u \in L^2(\Omega,\mathbb{R}^d) : \int_{\Omega} \langle u(x), x - Sx \rangle \, d\mu \ge 0 \text{ for all } S \in \mathcal{G}_N(\Omega,\mu) \right\},\$$

which coincide with the N-cyclically monotone maps, satisfy

$$\mathscr{G}_{N+1}(\Omega,\mu)^0 \subset \mathscr{G}_N(\Omega,\mu)^0,$$

for every $N \ge 1$. This can also be seen directly. Indeed, it is clear that a 2-involution is a 4-involution but not necessarily a 3-involution. On the other hand, assume that *u* is a 3-cyclically monotone operator. Then for any transformation $S : \Omega \to \Omega$, we have

$$\int_{\Omega} \langle u(x), x - Sx \rangle \, d\mu + \int_{\Omega} \langle u(Sx), Sx - S^2x \rangle \, d\mu + \int_{\Omega} \langle u(S^2x), S^2x - x \rangle \, d\mu \ge 0.$$

Now if S is measure-preserving, we have

$$\int_{\Omega} \langle u(x), x - Sx \rangle \, d\mu + \int_{\Omega} \langle u(x), x - Sx \rangle \, d\mu + \int_{\Omega} \langle u(S^2x), S^2x - x \rangle \, d\mu \ge 0,$$

and if $S^2 = I$, then $\int_{\Omega} \langle u(x), x - Sx \rangle d\mu \ge 0$, which means that $u \in \mathcal{G}_2(\Omega, \mu)^0$. Similarly, one can show that any (N+1)-cyclically monotone operator belongs to $\mathcal{G}_N(\Omega, \mu)^0$. In other words, $\mathcal{G}_{N+1}(\Omega, \mu)^0 \subset \mathcal{G}_N(\Omega, \mu)^0$ for all $N \ge 2$. Note that $\mathcal{G}_1(\Omega, \mu)^0 = \{I\}^0 = L^2(\Omega, \mathbb{R}^d)$, while

$$\mathcal{G}(\Omega, \mu)^0 = \bigcap_N \mathcal{G}_N(\Omega, \mu)^0$$

= { $u \in L^2(\Omega, \mathbb{R}^d), u = \nabla \phi$ for some convex function ϕ in $W^{1,2}(\mathbb{R}^d)$ },

in view of classical results of Rockafellar [1970] and Brenier [1991].

Remark 11. In [Ghoussoub and Moameni 2013b], the preceding result is extended to give a similar decomposition for any family of bounded measurable vector fields $u_1, u_2, \ldots, u_{N-1}$ on Ω . It is shown there that there exists a measure-preserving *N*-involution *S* on Ω and an *N*-antisymmetric Hamiltonian *H* on Ω^N such that for $i = 1, \ldots, N-1$, we have

$$u_i(x) = \nabla_{i+1} H(x, Sx, S^2 x, \dots, S^{N-1} x)$$
 for a.e. $x \in \Omega$.

Acknowledgement

We are grateful to the anonymous referee for a careful reading of this paper, which led to several improvements.

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Received January 7, 2013. Revised October 2, 2013.

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The Pacific Journal of Mathematics (ISSN 0030-8730) at the University of California, c/o Department of Mathematics, 798 Evans Hall #3840, Berkeley, CA 94720-3840, is published twelve times a year. Periodical rate postage paid at Berkeley, CA 94704, and additional mailing offices. POSTMASTER: send address changes to Pacific Journal of Mathematics, P.O. Box 4163, Berkeley, CA 94704-0163.

PJM peer review and production are managed by EditFLOW® from Mathematical Sciences Publishers.

PUBLISHED BY

 mathematical sciences publishers

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PACIFIC JOURNAL OF MATHEMATICS

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