

Variational representations for N-cyclically monotone vector fields

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Abstract

Given a convex bounded domain Ω in \mathbb{R}^d and an integer $N \geq 2$, we associate to any *jointly* Nmonotone (N-1)-tuplet $(u_1, u_2, ..., u_{N-1})$ of vector fields from Ω into \mathbb{R}^d , a Hamiltonian H on $\mathbb{R}^d \times$ \mathbb{R}^d ... $\times \mathbb{R}^d$, that is concave in the first variable, jointly convex in the last (N-1) variables such that for almost all $x \in \Omega$,

$$(u_1(x), u_2(x), ..., u_{N-1}(x)) = \nabla_{2,...,N} H(x, x, ..., x).$$

Moreover, H is N-sub-antisymmetric, meaning that $\sum_{i=0}^{N-1} H(\sigma^i(\mathbf{x})) \leq 0$ for all $\mathbf{x} = (x_1, ..., x_N) \in \Omega^N$, σ being the cyclic permutation on \mathbb{R}^d defined by $\sigma(x_1, x_2, ..., x_N) = (x_2, x_3, ..., x_N, x_1)$. Furthermore, H is N-antisymmetric in a sense to be defined below. This can be seen as an extension of a theorem of E. Krauss, which associates to any monotone operator, a concave-convex antisymmetric saddle function. We also give various variational characterizations of vector fields that are almost everywhere N-monotone. showing that they are dual to the class of measure preserving N-involutions on Ω .

Introduction 1

Given a domain Ω in \mathbb{R}^d , recall that a single-valued map u from Ω to \mathbb{R}^d is said to be *N*-cyclically monotone if for every cycle $x_1, ..., x_N, x_{N+1} = x_1$ of points in Ω , one has

$$\sum_{i=1}^{N} \left\langle u\left(x_{i}\right), x_{i} - x_{i+1} \right\rangle \ge 0.$$

$$\tag{1}$$

A classical theorem of Rockafellar [10] states that a map u from Ω to \mathbb{R}^d is N-cyclically monotone for every $N \geq 2$ if and only if

$$u(x) \in \partial \phi(x) \text{ for all } x \in \Omega,$$
 (2)

where $\phi : \mathbb{R}^d \to \mathbb{R}$ is a convex function. On the other hand, a result of E. Krauss [9] yields that u is a monotone map, i.e., a 2-cyclically monotone map, if and only if

$$u(x) \in \partial_2 H(x, x) \text{ for all } x \in \Omega,$$
(3)

where H is a concave-convex antisymmetric Hamiltonian on $\mathbb{R}^d \times \mathbb{R}^d$, and $\partial_2 H$ is the subdifferential of H as a convex function in the second variable.

In this paper, we extend the result of Krauss to the class of N-cyclically monotone vector fields, where $N \geq 3$. We shall give a representation for a family of (N-1) vector fields, which may or may not be individually N-cyclically monotone. Here is the needed concept.

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Definition 1 Let $u_1, ..., u_{N-1}$ be bounded vector fields from a domain $\Omega \subset \mathbb{R}^d$ into \mathbb{R}^d . We shall say that the (N-1)-tuple $(u_1, u_2, ..., u_{N-1})$ is jointly N-monotone, if for every cycle $x_1, ..., x_{N+\ell}$ of points in Ω such that $x_{N+i} = x_i$ for $1 \le i \le \ell$, one has

$$\sum_{i=1}^{N} \sum_{\ell=1}^{N-1} \langle u_l(x_i), x_i - x_{l+i} \rangle \ge 0.$$
(4)

Examples of jointly N-monotone families of vector fields:

- It is clear that (u, 0, 0, ..., 0) is jointly N-monotone if and only if u is N-monotone.
- More generally, if each u_{ℓ} is N-monotone, then the family $(u_1, u_2, ..., u_{N-1})$ is jointly N-monotone. Actually, one only needs that for $1 \leq \ell \leq N-1$, the vector field u_{ℓ} be (N, ℓ) -monotone, in the following sense: for every cycle $x_1, ..., x_{N+\ell}$ of points in Ω such that $x_{N+i} = x_i$ for $1 \leq i \leq \ell$, we have

$$\sum_{i=1}^{N} \left\langle u_{\ell}\left(x_{i}\right), x_{i} - x_{\ell+i} \right\rangle \geq 0.$$
(5)

This notion is sometimes weaker than N-monotonicity since if ℓ divides N, then it suffices for u to be $\frac{N}{\ell}$ -monotone in order to be an (N, ℓ) -monotone vector field. For example, if u_1 and u_3 are 4-monotone operators and u_2 is 2-monotone, then the triplet (u_1, u_2, u_3) is jointly 4-monotone.

• Another example is when (u_1, u_2, u_3) are vector fields such that u_2 is 2-monotone and

$$\langle u_1(x) - u_3(y), x - y \rangle \ge 0$$
 for every $x, y \in \mathbb{R}^d$.

In this case, the triplet (u_1, u_2, u_3) is jointly 4-monotone. In particular, if u_1 and u_2 are both 2-monotone, then the triplet (u_1, u_2, u_1) is jointly 4-monotone.

• More generally, it is easy to show that (u, u, ..., u) is jointly N-monotone if and only if u is 2-cyclically monotone.

In the sequel, we shall denote by σ the cyclic permutation on $\mathbb{R}^d \times \ldots \times \mathbb{R}^d$, defined by

$$\sigma(x_1, x_2, \dots, x_{N-1}, x_N) = (x_2, x_3, \dots, x_N, x_1),$$

and consider the family of continuous N-antisymmetric Hamiltonians on Ω^N , that is

$$\mathcal{H}_N(\Omega) = \{ H \in C(\Omega^N); \sum_{i=0}^{N-1} H(\sigma^i(x_1, ..., x_N)) = 0 \}$$
(6)

We shall say that H is N-sub-antisymmetric on Ω if

$$\sum_{i=0}^{N-1} H(\sigma^i(x_1, ..., x_N)) \le 0 \text{ on } \Omega^N \quad \text{and} \quad H(x, x, ..., x) = 0 \text{ on the diagonal.}$$
(7)

We shall also say that a function F of two variables is N-cyclically sub-antisymmetric on Ω , if

$$F(x,x) = 0$$
 and $\sum_{i=1}^{N} F(x_i, x_{i+1}) \le 0$ for all cyclic families $x_1, ..., x_N, x_{N+1} = x_1$ in Ω . (8)

Note that if a function $H(x_1, ..., x_N)$ N-sub-antisymmetric and if it only depends on the first two variables, then the function $F(x_1, x_2) := H(x_1, x_2, ..., x_N)$ is N-cyclically sub-antisymmetric.

We associate to any function H on Ω^N , the following functional on $\Omega \times (\mathbb{R}^d)^{N-1}$,

$$L_H(x, p_1, ..., p_{N-1}) = \sup\left\{\sum_{i=1}^{N-1} \langle p_i, y_i \rangle - H(x, y_1, ..., y_{N-1}); y_i \in \Omega\right\}.$$
(9)

Note that if Ω is convex and if H is convex in the last (N-1) variables, then L_H is nothing but the Legendre transform of \tilde{H} with respect to the last (N-1) variables, where \tilde{H} is the extension of H over $(\mathbb{R}^d)^N$, defined as: $\tilde{H} = H$ on Ω^N and $\tilde{H} = +\infty$ outside of Ω^N . Since H(x, ..., x) = 0 for any $H \in \mathcal{H}_N(\Omega)$, then for any such H, we have for $x \in \Omega$ and $p_1, ..., p_{N-1} \in \mathbb{R}^d$,

$$L_H(x, p_1, ..., p_{N-1}) \ge \sum_{i=1}^{N-1} \langle x, p_i \rangle.$$
(10)

To formulate variational principles for such vector fields, we shall consider the class of σ -invariant probability measures on Ω^N , which are those $\pi \in \mathcal{P}(\Omega^N)$ such that for all $h \in L^1(\Omega^N, d\pi)$, we have

$$\int_{\Omega^N} h(x_1, ..., x_N) d\pi = \int_{\Omega^N} h(\sigma(x_1, ..., x_N)) d\pi.$$
 (11)

We denote

$$\mathcal{P}_{\text{sym}}(\Omega^N) = \{ \pi \in \mathcal{P}(\Omega^N); \ \pi \ \sigma \text{-invariant probability on } \Omega^N \}.$$
(12)

For a given probability measure μ on Ω , we also consider the class

$$\mathcal{P}^{\mu}_{\rm sym}(\Omega^N) = \{ \pi \in \mathcal{P}_{\rm sym}(\Omega^N); \, \operatorname{proj}_1 \pi = \mu \}, \tag{13}$$

i.e., the set of all $\pi \in \mathcal{P}_{sym}(\Omega^N)$ with a given first marginal μ , meaning that

$$\int_{\Omega^N} f(x_1) \, d\pi(x_1, ..., x_N) = \int_{\Omega} f(x_1) \, d\mu(x_1) \text{ for every } f \in L^1(\Omega, \mu).$$
(14)

Consider now the set $\mathcal{S}(\Omega,\mu)$ of μ -measure preserving transformations on Ω , which can be identified with a closed subset of the sphere of $L^2(\Omega, \mathbb{R}^d)$. We shall also consider the subset of $\mathcal{S}(\Omega,\mu)$ consisting of *N*involutions, that is

$$\mathcal{S}_N(\Omega,\mu) = \{ S \in \mathcal{S}(\Omega,\mu); S^N = I \ \mu \text{ a.e.} \}.$$

2 Monotone vector fields and N-antisymmetric Hamiltonians

In this section, we establish the following extension of a theorem of Krauss.

Theorem 2 Let $N \ge 2$ be an integer, and consider $u_1, ..., u_{N-1}$ to be bounded vector fields from a convex domain $\Omega \subset \mathbb{R}^d$ into \mathbb{R}^d .

1. If the (N-1)-tuple $(u_1, ..., u_{N-1})$ is jointly N-monotone, then there exists an N-sub-antisymmetric Hamiltonian H that is concave in the first variable, convex in the other (N-1) variables such that

$$(u_1(x), ..., u_{N-1}(x)) = \nabla_{2,...,N} H(x, x, ..., x) \quad for \ a.e. \ x \in \Omega.$$
(15)

Moreover, H is N-antisymmetric in the following sense

$$H(x_1, x_2, ..., x_N) + H_{2,...,N}(x_1, x_2, ..., x_N) = 0,$$
(16)

where $H_{2,...,N}$ is the concavification of the function $K(\mathbf{x}) = \sum_{i=1}^{N-1} H(\sigma^i(\mathbf{x}))$ with respect to the last (N-1) variables.

Furthermore, there exists a continuous N-antisymmetric Hamiltonian \overline{H} on Ω^N , such that

$$L_{\bar{H}}(x, u_1(x), u_2(x), ..., u_{N-1}(x)) = \sum_{i=1}^{N-1} \langle u_i(x), x \rangle \text{ for all } x \in \Omega.$$
(17)

2. Conversely, if $(u_1, ..., u_{N-1})$ satisfy (15) for some N-sub-antisymmetric Hamiltonian H that is concave in the first variable, convex in the other variables, then the (N-1)-tuple $(u_1, ..., u_{N-1})$ is jointly Nmonotone. **Remark 3** Note that in the case N = 2, $K(\mathbf{x}) = H(x_2, x_1)$ is concave with respect to x_2 , hence $H_2(x_1, x_2) = H(x_2, x_1)$, and (16) becomes

$$H(x_1, x_2) + H(x_2, x_1) = 0,$$

thus H is antisymmetric, recovering well-known results [9], [4], [7], [8].

We start with the following lemma.

Lemma 4 Assume the (N-1)-tuple of bounded vector fields $(u_1, ..., u_{N-1})$ on Ω is jointly N-monotone. Let $f(x_1, ..., x_n) := \sum_{l=1}^{N-1} \langle u_l(x_1), x_1 - x_{l+1} \rangle$ and consider the function $\tilde{f}(x_1, ..., x_n)$ to be the convexification of f with respect to the first variable, that is

$$\tilde{f}(x_1, x_2, ..., x_N) = \inf\left\{\sum_{k=1}^n \lambda_k f\left(x_1^k, x_2, ..., x_N\right) : n \in \mathbb{N}, \lambda_k \ge 0, \sum_{k=1}^n \lambda_k = 1, \sum_{k=1}^n \lambda_k x_1^k = x_1\right\}.$$
(18)

Then, \tilde{f} satisfies the following properties:

- 1. $f \geq \tilde{f}$ on Ω^N ;
- 2. \tilde{f} is convex in the first variable and concave with respect to the other variables;
- 3. $\tilde{f}(x, x, ..., x) = 0$ for each $x \in \Omega$,
- 4. \tilde{f} satisfies

$$\sum_{i=0}^{N-1} \tilde{f}(\sigma^{i}(x_{1},...,x_{N})) \ge 0 \text{ on } \Omega^{N}.$$
(19)

Proof: Since the (N-1)-tuple $(u_1, ..., u_{N-1})$ is jointly N-monotone, it is easy to see that the function

$$f(x_1, ..., x_n) := \sum_{l=1}^{N-1} \langle u_l(x_1), x_1 - x_{l+1} \rangle$$

is linear in the last (N-1) variables, that f(x, x, ..., x) = 0, and that

$$\sum_{i=0}^{N-1} f(\sigma^i(x_1, ..., x_N)) \ge 0 \text{ on } \Omega^N.$$
(20)

It is also clear that $f \ge \tilde{f}$, that \tilde{f} is convex with respect to the first variable x_1 , and that it is concave with respect to the other variables $x_2, ..., x_N$, since f itself is concave (actually linear) with respect to $x_2, ..., x_n$. We now show that \tilde{f} satisfies (19).

For that, we fix $x_1, x_2, ..., x_N$ in Ω and consider $(x_1^k)_{k=1}^n$ in Ω , and $(\lambda_k)_k$ in \mathbb{R} such that $\lambda_k \ge 0$ such that $\sum_{k=1}^n \lambda_k = 1$ and $\sum_{k=1}^n \lambda_k x_1^k = x_1$. For each k, we have

$$f(x_1^k, x_2, ..., x_N) + f(x_2, ..., x_N, x_1^k) + ... + f(x_N, x_1^k, x_2, ..., x_{N-1}) \ge 0.$$

Multiplying by λ_k , summing over k, and using that f is linear in the last (N-1)-variables, we have

$$\sum_{k=1}^{n} \lambda_k f(x_1^k, x_2, ..., x_N) + f(x_2, ..., x_N, x_1) + ... + f(x_N, x_1, x_2, ..., x_{N-1}) \ge 0.$$

By taking the infimum, we obtain

$$\tilde{f}(x_1, x_2, ..., x_N) + \sum_{i=1}^{N-1} f(\sigma^i(x_1, x_2, ..., x_N)) \ge 0.$$

Let now $n \in \mathbb{N}$, $\lambda_k \ge 0$, $x_N^k \in \Omega$ be such that $\sum_{k=1}^n \lambda_k = 1$ and $\sum_{k=1}^n \lambda_k x_2^k = x_2$. We have for every $1 \le k \le n$,

$$\tilde{f}(x_1, x_2^k, x_3, ..., x_N) + f(x_2^k, x_3, ..., x_1) + ... + f(x_N, x_1, x_2^k, x_3, ..., x_{N-1}) \ge 0.$$

Multiplying by λ_k , summing over k and using that \tilde{f} is convex in the first variable and f is linear in the last (N-1)-variables, we obtain

$$\tilde{f}(x_1, x_2, x_3, ..., x_N) + \sum_{k=1}^n \lambda_k f(x_2^k, x_3, ..., x_1) + ... + f(x_N, x_1, x_2, x_3, ..., x_{N-1})$$

$$\geq \sum_{k=1}^n \lambda_k \tilde{f}(x_1, x_2^k, x_3, ..., x_N) + \sum_{k=1}^n \lambda_k f(x_2^k, x_3, ..., x_1) + ... + \sum_{k=1}^n \lambda_k f(x_N, x_1, x_2^k, x_3, ..., x_{N-1}) \geq 0.$$

By taking the infimum over all possible such choices, we get

 $\tilde{f}(x_1, x_2, x_3, \dots, x_N) + \tilde{f}(x_2, x_3, \dots, x_1) + \dots + f(x_N, x_1, x_2, x_3, \dots, x_{N-1}) \ge 0.$

By repeating this procedure with $x_3, ..., x_{N-1}$, we get

$$\sum_{i=0}^{N-2} \tilde{f}\left(\sigma^{i}(x_{1}, x_{2}, ..., x_{N})\right) + f\left(x_{N}, x_{1}, x_{2}, x_{3}, ..., x_{N-1}\right) \ge 0.$$

Finally, since

$$f(x_N, x_1, x_2, x_3, ..., x_{N-1}) \ge -\sum_{i=0}^{N-2} \tilde{f}(\sigma^i(x_1, x_2, ..., x_N)).$$

and since \tilde{f} is concave in the last (N-1) variables, we have for fixed x_1, x_2, \dots, x_{N-1} , that the function

$$x_N \to -\sum_{i=0}^{N-2} \tilde{f}\left(\sigma^i(x_1, x_2, ..., x_N)\right)$$

is a convex minorant of $x_N \to f(x_N, x_1, x_2, x_3, ..., x_{N-1})$. It follows that

$$f(x_N, x_1, x_2, x_3, ..., x_{N-1}) \ge \tilde{f}(x_N, x_1, x_2, x_3, ..., x_{N-1}) \ge -\sum_{i=0}^{N-2} \tilde{f}\left(\sigma^i(x_1, x_2, ..., x_N)\right),$$

which finally implies that $\sum_{i=0}^{N-1} \tilde{f}(\sigma^i(x_1, x_2, ..., x_N)) \ge 0$. This clearly implies that $\tilde{f}(x, x, ..., x) \ge 0$ for any $x \in \Omega$. On the other hand, since $\tilde{f}(x, x, ..., x) \le 0$. f(x, x, ..., x) = 0, we get that f(x, x, ..., x) = 0 for all $x \in \Omega$.

Proof of Theorem 2: Assume the (N-1)-tuple of vector fields $(u_1, ..., u_{N-1})$ is jointly N-monotone on Ω , and consider the function $f(x_1, ..., x_n) := \sum_{l=1}^{N-1} \langle u_l(x_1), x_1 - x_{l+1} \rangle$ as well as its convexification with respect to the first variable $f(x_1, ..., x_n)$.

By Lemma 4, the function $\psi(x_1,...,x_n) := -\tilde{f}(x_1,...,x_n)$ satisfies the following properties

- (i) $x_1 \to \psi(x_1, ..., x_n)$ is concave;
- (ii) $(x_2, x_3, ..., x_N) \rightarrow \psi(x_1, ..., x_n)$ is convex;
- (iii) $\psi(x_1, ..., x_n) \ge -f(x_1, ..., x_n) = \sum_{l=1}^{N-1} \langle u_l(x_1), x_{l+1} x_1 \rangle;$
- (iv) ψ is N-sub-antisymmetric.

Consider now the family \mathcal{H} of functions $H: \Omega^N \to \mathbb{R}$ such that

1.
$$H(x_1, x_2, ..., x_N) \ge \sum_{l=1}^{N-1} \langle u_l(x_1), x_{l+1} - x_1 \rangle$$
 for every N-tuple $(x_1, ..., x_N)$ in Ω^N ;

- 2. H is concave in the first variable;
- 3. *H* is jointly convex in the last (N-1) variables;
- 4. *H* is *N*-sub-antisymmetric.

Note that $\mathcal{H} \neq \emptyset$ since ψ belongs to \mathcal{H} . Moreover, by N-subsymmetry, any $H \in \mathcal{H}$ satisfies for all $\mathbf{x} = (x_1, ..., x_N) \in \Omega^N$,

$$H(\mathbf{x}) \le -\sum_{i=1}^{N-1} H(\sigma^{i}(\mathbf{x})) \le -\sum_{i=1}^{N-1} \psi(\sigma^{i}(\mathbf{x})).$$
(21)

This also yields that

$$\sum_{\ell=1}^{N-1} \langle u_{\ell}(x_1), x_{\ell+1} - x_1 \rangle \le H(\mathbf{x}) \le -\sum_{i=2}^{N} \sum_{\ell=1}^{N-1} \langle u_{\ell}(x_i), x_i - x_{i+\ell} \rangle,$$
(22)

where we denote $x_{i+N} := x_i$ for $i = 1, ..., \ell$. This yields that H(x, x, ..., x) = 0 for every $H \in \mathcal{H}$ and any $x \in \Omega$.

On the other hand, it is easy to see that every directed family $(H_i)_i$ in \mathcal{H} has a supremum $H_{\infty} \in \mathcal{H}$, meaning that \mathcal{H} is a Zorn family, and therefore it has a maximal element H.

Consider now the function

$$\bar{H}(\mathbf{x}) = \frac{(N-1)H(\mathbf{x}) - \sum_{i=1}^{N-1} H(\sigma^i(\mathbf{x}))}{N}$$

and note that

(i) \overline{H} is N-antisymmetric, since

$$\bar{H}(\mathbf{x}) = \frac{1}{N} \sum_{i=1}^{N-1} [H(\mathbf{x}) - H(\sigma^i(\mathbf{x}))],$$

and each $K_i(\mathbf{x}) := H(\mathbf{x}) - H(\sigma^i(\mathbf{x}))$ is N-antisymmetric.

(ii) $\overline{H} \geq H$ on Ω^N , since

$$N[\bar{H}(\mathbf{x}) - H(\mathbf{x})] = -\sum_{i=0}^{N-1} H(\sigma^i(\mathbf{x})) \ge 0,$$

because H itself is N-sub-antisymmetric.

The maximality of H would have implied that $H = \overline{H}$ is N-antisymmetric if only \overline{H} was jointly convex in the last (N - 1)-variables, but since this is not necessarily the case, we consider for $\mathbf{x} = (x_1, x_2, ..., x_N)$, the function

$$K(x_1, x_2, ..., x_N) = K(\mathbf{x}) := -\sum_{i=1}^{N-1} H(\sigma^i(\mathbf{x})),$$

which is already concave in the first variable x_1 . Its convexification in the last (N-1)-variables, that is

$$K^{2,...,N}(\mathbf{x}) = \inf\left\{\sum_{i=1}^{n} \lambda_i K(x_1, x_2^i, ..., x_N^i); \, \lambda_i \ge 0, \sum_{i=1}^{n} \lambda_i (x_2^i, ..., x_N^i, 1) = (x_2, ..., x_N, 1)\right\},\$$

is still concave in the first variable, but is now convex in the last (N-1) variables. Moreover,

$$H \le K^{2,...,N} \le K = -\sum_{i=1}^{N-1} H \circ \sigma^{i}.$$
 (23)

Indeed, $K^{2,...,N} \leq K$ from the definition of $K^{2,...,N}$, while $H \leq K^{2,...,N}$ because $H \leq K$ and H is already convex in the last (N-1)-variables. It follows that

$$H \leq \frac{(N-1)H + K^{2,\dots,N}}{N} \leq \frac{(N-1)H + K}{N} = \frac{(N-1)H - \sum_{i=1}^{N-1} H \circ \sigma^{i}}{N} = \bar{H}$$

The function $H' = \frac{(N-1)H + K^{2,...,N}}{N}$ belongs to the family \mathcal{H} and therefore H = H' by the maximality of H. This finally yields that H is N-sub-antisymmetric, that H(x, x, x) = 0 for all $x \in \Omega$ and that

$$H(\mathbf{x}) + H_{2,\dots,N}(\mathbf{x}) = 0$$
 for every $\mathbf{x} \in \Omega^N$.

where $H_{2,...,N} = -K^{2,...,N}$, which for a fixed x_1 , is nothing but the concavification of $(x_2,...,x_N) \rightarrow K^{2,...,N}$ $\sum_{i=1}^{N-1} H(\sigma^i(x_1, x_2, ..., x_N)).$ Note now that since for any $x_1, ..., x_N$ in Ω ,

$$H(x_1, x_2, \dots x_N) \ge \sum_{\ell=1}^{N-1} \langle u_\ell(x_1), x_{\ell+1} - x_1 \rangle,$$
(24)

and

$$H(x_1, x_1, ..., x_1) = 0, (25)$$

we have

$$H(x_1, x_2, ..., x_N) - H(x_1, ..., x_1) \ge \sum_{\ell=1}^{N-1} \langle u_\ell(x_1), x_{\ell+1} - x_1 \rangle.$$
(26)

Since H is convex in the last (N-1) variables, this means that for all $x \in \Omega$, we have

 $(u_1(x), u_2(x), \dots, u_{N-1}(x)) \in \partial_{2,\dots,N} H(x, x, \dots, x).$ (27)

as claimed in (15). Note that this also yield that

$$L_H(x, u_1(x), ..., u_{N-1}(x)) + H(x, x, ..., x) = \sum_{\ell=1}^{N-1} \langle u_\ell(x), x \rangle \text{ for all } x \in \Omega.$$

In other words, $L_H(x, u_1(x), ..., u_{N-1}(x)) = \sum_{\ell=1}^{N-1} \int_{\Omega} \langle u_\ell(x), x \rangle$ for all $x \in \Omega$. As above, consider

$$\bar{H}(\mathbf{x}) = \frac{(N-1)H(\mathbf{x}) - \sum_{i=1}^{N-1} H(\sigma^i(\mathbf{x}))}{N}.$$

We have that $\overline{H} \in \mathcal{H}_N(\Omega)$ and $\overline{H} \ge H$, and therefore $L_{\overline{H}} \le L_H$. On the other hand, we have for all $x \in \Omega$,

$$L_{\bar{H}}(x, u_1(x), ..., u_{N-1}(x)) = L_{\bar{H}}(x, u_1(x), ..., u_{N-1}(x)) + \bar{H}(x, x, ..., x) \ge \sum_{\ell=1}^{N-1} \langle u_\ell(x), x \rangle.$$

To prove (17), we use the appendix in [6] to deduce that for i = 2, ..., N, the gradients $\nabla_i H(x, x, ..., x)$ actually exist for a.e. x in Ω .

The converse is straightforward since if (27) holds, then (26) does, and since we also have (25), then the property that $(u_1, ..., u_{N-1})$ is jointly N-monotone follows from (24) and the sub-antisymmetry of H.

In the case of a single N-monotone vector field, we can obviously apply the above theorem to the (N-1)tuple (u, 0, ..., 0) which is then N-monotone to find a N-sub-antisymmetric Hamiltonian H, which is concave in the first variable, convex in the last (N-1) variables such that

$$(-u(x), u(x), 0, ..., 0) = \nabla H(x, x, ..., x) \quad \text{for a.e. } x \in \Omega.$$
 (28)

However, in this case we can restrict ourselves to N-cyclically sub-antisymmetric functions of two variables and establish the following extension of the Theorem of Krauss.

Theorem 5 If u is N-cyclically monotone on Ω , then there exists a concave-convex function of two variables F that is N-cyclically sub-antisymmetric, such that

$$(-u(x), u(x) \in \partial F(x, x) \text{ for all } x \in \Omega,$$
(29)

where ∂H is the sub-differential of H as a concave-convex function [11]. Moreover,

$$u(x) = \nabla_2 F(x, x) \text{ for a.e. } x \in \Omega.$$
(30)

Proof: Let $f(x,y) = \langle u(x), x - y \rangle$ and let $f^1(x,y)$ be its convexification in x for fixed y, that is

$$f^{1}(x,y) = \inf\left\{\sum_{k=1}^{n} \lambda_{k} f(x_{k},y) : \lambda_{k} \ge 0, \sum_{k=1}^{n} \lambda_{k} = 1, \sum_{k=1}^{n} \lambda_{k} x_{k} = x\right\}.$$
(31)

Since f(x,x) = 0, f is linear in y, and $\sum_{i=1}^{N} f(x_i, x_{i+1}) \ge 0$ for any cyclic family $x_1, ..., x_N, x_{N+1} = x_1$ in Ω , it is easy to show that $f \ge f^1$ on Ω , f^1 is convex in the first variable and concave with respect to the second, $f^1(x,x) = 0$ for each $x \in \Omega$, and that f^1 is N-cyclically supersymmetric in the sense that for any cyclic family $x_1, ..., x_N, x_{N+1} = x_1$ in Ω , we have $\sum_{i=1}^{N} f^1(x_i, x_{i+1}) \ge 0$. Consider now $F(x,y) = -f^1(x,y)$ and note that $x \to F(x,y)$ is concave, $y \to F(x,y)$ is convex, $F(x,y) \ge 0$.

Consider now $F(x, y) = -f^1(x, y)$ and note that $x \to F(x, y)$ is concave, $y \to F(x, y)$ is convex, $F(x, y) \ge -f(x, y) = \langle u(x), y - x \rangle$ and F is N-cyclically sub-antisymmetric. By the antisymmetry, we have

$$\langle u(x_1), x_2 - x_1 \rangle \le F(x_1, x_2) \le \langle u(x_2), x_2 - x_1 \rangle,$$
 (32)

which yields that $(-u(x), u(x)) \in \partial F(x, x)$ for all $x \in \Omega$.

Since F is anti-symmetric and concave-convex, the possibly multivalued map $x \to \partial_2 F(x, x)$ is monotone on Ω , and therefore single-valued and differentiable almost everywhere [10]. This completes the proof.

Remark 6 Note that we cannot expect to have a function F such that $\sum_{i=1}^{N} F(x_i, x_{i+1}) = 0$ for all cyclic families $x_1, ..., x_N, x_{N+1} = x_1$ in Ω . Actually, we believe that the only function satisfying such an N-antisymmetry for $N \ge 3$ must be of the form F(x, y) = f(x) - f(y). This is the reason why one needs to consider functions of N-variables in order to get N-antisymmetry. In other words, the function defined by

$$H(x_1, x_2, ..., x_N) := \frac{(N-1)F(x_1, x_2) - \sum_{i=2}^{N-1} F(x_i, x_{i+1})}{N},$$
(33)

is N-antisymmetric in the sense of (6) and $H(x_1, x_2..., x_N) \ge F(x_1, x_2)$ for all $(x_1, x_2..., x_N)$ in Ω^N .

3 Variational characterization of monotone vector fields

In order to simplify the exposition, we shall always assume in the sequel that $d\mu$ is Lebesgue measure dx normalized to be a probability on Ω . We shall also assume that Ω is convex and that its boundary has measure zero.

Theorem 7 Let $u_1, ..., u_{N-1} : \Omega \to \mathbb{R}^d$ be bounded measurable vector fields. The following properties are then equivalent:

- 1. The (N-1)-tuple $(u_1, ..., u_{N-1})$ is jointly N-monotone a.e., that is there exists a measure zero set Ω_0 such that $(u_1, ..., u_{N-1})$ is jointly N-monotone on $\Omega \setminus \Omega_0$.
- 2. The infimum of the following Monge-Kantorovich problem

$$\inf\left\{\int_{\Omega^{N}}\sum_{\ell=1}^{N-1} \langle u(x_{1}), x_{1} - x_{\ell+1} \rangle d\pi(x_{1}, x_{2}, ..., x_{N})); \ \pi \in \mathcal{P}_{\text{sym}}^{\mu}(\Omega^{N})\right\}$$
(34)

is equal to zero, and is therefore attained by the push-forward of μ by the map $x \to (x, x, ..., x)$.

3. $(u_1, ..., u_{N-1})$ is in the polar of $\mathcal{S}_N(\Omega, \mu)$ in the following sense,

$$\inf\left\{\int_{\Omega}\sum_{\ell=1}^{N-1} \langle u_{\ell}(x), x - S^{\ell}x \rangle \, d\mu; S \in \mathcal{S}_{N}(\Omega, \mu)\right\} = 0.$$
(35)

4. The following holds:

$$\inf\left\{\int_{\Omega}\sum_{\ell=1}^{N-1}|u_{\ell}(x)-S^{\ell}x|^{2}d\mu;S\in\mathcal{S}_{N}(\Omega,\mu)\right\}=\sum_{\ell=1}^{N-1}\int_{\Omega}|u_{\ell}(x)-x|^{2}d\mu.$$
(36)

5. There exists a N-sub-antisymmetric Hamiltonian H which is concave in the first variable, convex in the last (N-1) variables such that

$$(u_1(x), ..., u_{N-1}(x)) = \nabla_{2,...,N} H(x, x, ..., x) \quad for \ a.e. \ x \in \Omega.$$
(37)

Moreover, H is N-symmetric in the sense of (16).

6. The following duality holds:

$$\inf\{\int_{\Omega} L_H(x, u_1(x), \dots, u_{N-1}(x))d\mu; \ H \in \mathcal{H}_N(\Omega)\} = \sup\{\int_{\Omega} \sum_{\ell=1}^{N-1} \langle u_\ell(x), S^\ell x \rangle \, d\mu; S \in \mathcal{S}_N(\Omega, \mu)\}$$

and the latter is attained at the identity map.

We start with the following lemma, which identifies those probabilities in $\mathcal{P}^{\mu}_{\text{sym}}(\Omega^N)$ that are carried by graphs of functions from Ω to Ω^N .

Lemma 8 Let $S: \Omega \to \Omega$ be a μ -measurable map, then the following properties are equivalent:

- 1. The image of μ by the map $x \to (x, Sx, ..., S^{N-1}x)$ belongs to $\mathcal{P}^{\mu}_{sym}(\Omega^N)$.
- 2. S is μ -measure preserving and $S^N(x) = x \mu$ -a.e.
- 3. For any bounded Borel measurable N-antisymmetric H on Ω^N , we have $\int_{\Omega} H(x, Sx, ..., S^{N-1}x) d\mu = 0$.

Proof. It is clear that 1) implies 3) since $\int_{\Omega^N} H(\mathbf{x}) d\pi(\mathbf{x}) = 0$ for any *N*-antisymmetric Hamiltonian *H* and any $\pi \in \mathcal{P}^{\mu}_{sym}(\Omega^N)$.

That 2) implies 1) is also straightforward since if π is the push-forward of μ by a map of the form $x \to (x, Sx, ..., S^{N-1}x)$, where S is a μ -measure preserving S with $S^N x = x \mu$ a.e. on Ω , then for all $h \in L^1(\Omega^N, d\pi)$, we have

$$\begin{split} \int_{\Omega^N} h(x_1, ..., x_N) d\pi &= \int_{\Omega^N} h(x, Sx, ..., S^{N-1}x) \, d\mu(x) = \int_{\Omega^N} h(Sx, S^2x, ..., S^{N-1}x, S^Nx) \, d\mu(x) \\ &= \int_{\Omega^N} h(Sx, S^2x, ..., S^{N-1}x, x) \, d\mu(x) = \int_{\Omega^N} h(\sigma(x_1, ..., x_N)) d\pi. \end{split}$$

We now prove that 2) and 3) are equivalent. Assuming first that S is μ -measure preserving such that $S^N = I$ μ a.e., then for every Borel bounded N-antisymmetric H, we have

$$\begin{split} \int_{\Omega} H(x, Sx, S^2x, ..., S^{N-1}x) d\mu &= \int_{\Omega} H(Sx, S^2x, ..., S^{N-1}x, x) d\mu \\ &= ... = \int_{\Omega} H(S^{N-1}x, x, Sx, ..., S^{N-2}x) d\mu. \end{split}$$

Since H is N-antisymmetric, we can see that

$$H(x, Sx, ..., S^{N-1}x) + H(Sx, S^2x, ..., S^{N-1}x, x) + ... + H(S^{N-1}x, x, Sx, ..., S^{N-2}x) = 0.$$

It follows that $N \int_{\Omega} H(x, Sx, S^2x, .., S^{N-1}x) d\mu = 0.$

For the reverse implication, assume $\int_{\Omega} H(x, Sx, S^2x, ..., S^{N-1}x)d\mu = 0$ for every N-antisymmetric Hamiltonian H. By testing this identity with the Hamiltonians

$$H(x_1, x_2, ..., x_N) = f(x_1) - f(x_i),$$

where f is any continuous function on Ω , one gets that S is μ -measure preserving. Now take the Hamiltonian

$$H(x_1, x_2, ..., x_N) = |x_1 - Sx_N| - |Sx_1 - x_2| - |x_2 - Sx_1| + |Sx_2 - x_3|$$

Note that $H \in \mathcal{H}_N(\Omega)$ since it is of the form $H(x_1, ..., x_N) = f(x_1, x_2, x_N) - f(x_2, x_3, x_1)$. Now test the above identity with such an H to obtain

$$0 = \int_{\Omega} H(x, Sx, S^2x, ..., S^{N-1}x) d\mu = \int_{\Omega} |x - SS^{N-1}x| \, d\mu.$$

It follows that $S^N = I \ \mu$ a.e. on ω , and we are done.

Proof of Theorem 7: To show that (1) implies (2), it suffices to notice that if π is a σ -invariant probability measure on Ω^N such that $\operatorname{proj}_1 \pi = \mu$, then

$$\begin{split} \int_{\Omega^{N}} \sum_{\ell=1}^{N-1} \langle u_{\ell}(x_{1}), x_{1} - x_{\ell+1} \rangle d\pi \left(x_{1}, ..., x_{N} \right) &= \frac{1}{N} \sum_{i=1}^{N} \int_{\Omega^{N}} \sum_{\ell=1}^{N-1} \langle u_{\ell} \left(x_{i} \right), x_{i} - x_{i+\ell} \rangle d\pi \left(x_{1}, ..., x_{N} \right) \\ &= \frac{1}{N} \int_{\Omega^{N}} \left(\sum_{i=1}^{N} \sum_{\ell=1}^{N-1} \langle u_{\ell} \left(x_{i} \right), x_{i} - x_{i+\ell} \rangle \right) d\pi \left(x_{1}, ..., x_{N} \right) \\ &\geq 0, \end{split}$$

since $(u_1, ..., u_{N-1})$ is jointly N-monotone. On the other hand, if π is the σ -invariant measure obtained by taking the image of $\mu := dx$ by $x \to (x, ..., x)$, then

$$\int_{\Omega^N} \sum_{\ell=1}^{N-1} \langle u_\ell(x_1), x_1 - x_{\ell+1} \rangle d\pi (x_1, ..., x_N) = 0.$$

To show that (2) implies (3), let S be a μ -measure preserving transformation on Ω such that $S^N = I \mu$ a.e. on Ω . Then the image π_S of μ by the map

$$x \to \left(x, Sx, S^2x, \dots, S^{N-1}x\right)$$

is σ -invariant, hence

$$\int_{\Omega^N} \sum_{\ell=1}^{N-1} \langle u_\ell(x_1), x_1 - x_{\ell+1} \rangle d\pi_S(x_1, ..., x_N) = \int_{\Omega} \sum_{\ell=1}^{N-1} \langle u_\ell(x), x - S^\ell x \rangle d\mu \ge 0.$$

By taking S = I, we get that the infimum is necessarily zero.

The equivalence of (3) and (4) follows immediately from developing the square.

We now show that (3) implies (1). For that take N points $x_1, x_2, ..., x_N$ in Ω , and let R > 0 be such that $B(x_i, R) \subset \Omega$. Consider the transformation

$$S_{R}(x) = \begin{cases} x - x_{1} + x_{2} \text{ for } x \in B(x_{1}, R) \\ x - x_{2} + x_{3} \text{ for } x \in B(x_{2}, R) \\ \dots \\ x - x_{N} + x_{1} \text{ for } x \in B(x_{N}, R) \\ x \text{ otherwise} \end{cases}$$

It is easy to see that S_R is a measure preserving transformation and that $S_R^N = Id$. We then have

$$0 \le \int_{\Omega} \sum_{\ell=1}^{N-1} \langle u_{\ell}(x), x - S_{R}^{\ell} x \rangle \, d\mu \le \sum_{i=1}^{N} \int_{B(x_{i},R)} \sum_{\ell=1}^{N-1} \langle u_{\ell}(x), x_{i} - x_{\ell+i} \rangle \, d\mu.$$

Letting $R \to 0$, we get from Lebesgue's density theorem, that

$$\frac{1}{|B(x_i,R)|} \int_{B(x_i,R)} \langle u_{\ell}(x), x_i - x_{\ell+i} \rangle \, d\mu \to \langle u_{\ell}(x_i), x_i - x_{\ell+i} \rangle \,,$$

from which follows that $(u_1, ..., u_{N-1})$ are jointly N-monotone a.e. on Ω .

The fact that (1) is equivalent to (5) follows immediately from Theorem 2. To prove that 5) implies 6) note that for all $p_i \in \mathbb{R}^d$, $x \in \Omega$, $y_i \in \Omega$, i = 1, ..., N - 1,

$$L_H(x, p_1, ..., p_{N-1}) + H(x, y_1, ..., y_{N-1}) \ge \sum_{i=1}^{N-1} \langle p_i, y_i \rangle,$$

which yields that for any $S \in \mathcal{S}_N(\Omega, \mu)$,

$$\int_{\Omega} [L_H(x, u_1(x), ..., u_{N-1}(x)) \, d\mu + H(x, Sx, ..., S^{N-1}x)] \, d\mu \ge \int_{\Omega} \sum_{\ell=1}^{N-1} \langle u_\ell(x), S^\ell x \rangle \, d\mu.$$

If $H \in \mathcal{H}_N(\Omega)$ and $S \in \mathcal{S}_N(\Omega, \mu)$, we then have $\int_{\Omega} H(x, Sx, ..., S^{N-1}x) d\mu = 0$, and therefore

$$\int_{\Omega} L_H(x, u_1(x), ..., u_{N-1}(x)) \, d\mu \ge \int_{\Omega} \sum_{\ell=1}^{N-1} \langle u_\ell(x), S^\ell x \rangle \, d\mu.$$

If now H is the N-sub-antisymmetric Hamiltonian obtained by 5), which is concave in the first variable, convex in the last (N-1) variables, then

$$L_{H}(x, u_{1}(x), ..., u_{N-1}(x)) + H(x, x, ..., x) = \sum_{\ell=1}^{N-1} \langle u_{\ell}(x), x \rangle \text{ for all } x \in \Omega \setminus \Omega_{0},$$

and therefore $\int_{\Omega} L_H(x, u_1(x), ..., u_{N-1}(x)) d\mu = \sum_{\ell=1}^{N-1} \int_{\Omega} \langle u_\ell(x), x \rangle d\mu$. Consider now

$$\bar{H}(\mathbf{x}) = \frac{(N-1)H(\mathbf{x}) - \sum_{i=1}^{N-1} H(\sigma^i(\mathbf{x}))}{N}$$

As before, we have that $\bar{H} \in \mathcal{H}_N(\Omega)$ and $\bar{H} \ge H$. Since $L_{\bar{H}} \le L_H$, we have that $\int_{\Omega} L_{\bar{H}}(x, u_1(x), ..., u_{N-1}(x)) d\mu = 0$ $\sum_{\ell=1}^{N-1} \int_{\Omega} \langle u_{\ell}(x), x \rangle \, d\mu$ and (6) is proved.

Finally, note that (6) readily implies (3), which means that $(u_1, ..., u_{N-1})$ is then jointly N-monotone. \Box

We now consider again the case of a single N-cyclically monotone vector field.

Corollary 9 Let $u: \Omega \to \mathbb{R}^d$ be a bounded measurable vector field. The following properties are then equivalent:

- 1. u is N-cyclically monotone a.e., that is there exists a measure zero set Ω_0 such that u is N-cyclically monotone on $\Omega \setminus \Omega_0$.
- 2. The infimum of the following Monge-Kantorovich problem

$$\inf\{\int_{\Omega^N} \langle u(x_1), x_1 - x_2 \rangle d\pi(\mathbf{x}); \ \pi \in \mathcal{P}^{\mu}_{\text{sym}}(\Omega^N)\}$$
(38)

is equal to zero, and is therefore attained by the push-forward of μ by the map $x \to (x, x, ..., x)$.

3. The vector field u is in the polar of $\mathcal{S}_N(\Omega,\mu)$, that is

$$\inf\{\int_{\Omega} \langle u(x), x - Sx \rangle \, d\mu; S \in \mathcal{S}_N(\Omega, \mu)\} = 0.$$
(39)

4. The projection of u on $\mathcal{S}_N(\Omega,\mu)$ is the identity map, that is

$$\inf\{\int_{\Omega} |u(x) - Sx|^2 d\mu; S \in \mathcal{S}_N(\Omega, \mu)\} = \int_{\Omega} |u(x) - x|^2 d\mu.$$

$$\tag{40}$$

5. There exists a N-cyclically sub-antisymmetric function H of two variables, which is concave in the first variable, convex in the second variable such that

$$u(x) = \nabla_2 H(x, x) \quad \text{for a.e. } x \in \Omega.$$
(41)

6. The following duality holds:

$$\inf\{\int_{\Omega} L_H(x, u(x), 0, ..., 0) d\mu; \ H \in \mathcal{H}_N(\Omega)\} = \sup\{\int_{\Omega} \langle u(x), Sx \rangle \ d\mu; S \in \mathcal{S}_N(\Omega, \mu)\}$$

and the latter is attained at the identity map.

Proof: This is an immediate application of Theorem 7 applied to the (N-1)-tuplet vector fields (u, 0, ..., 0), which is clearly jointly N-monotone on $\Omega \setminus \Omega_0$, whenever u is N-monotone on $\Omega \setminus \Omega_0$.

Remark 10 Note that the sets of μ -measure preserving N-involutions $(\mathcal{S}_N(\Omega, \mu))_N$ do not form a nested family, that is $\mathcal{S}_N(\Omega, \mu)$ is not necessarily included in $\mathcal{S}_M(\Omega, \mu)$, whenever $N \leq M$, unless of course M is a multiple of N. On the other hand, the above theorem shows that their polar sets, i.e.,

$$\mathcal{S}_N(\Omega,\mu)^0 = \{ u \in L^2(\Omega,\mathbb{R}^d); \int_\Omega \langle u(x), x - Sx \rangle \, d\mu \ge 0 \text{ for all } S \in \mathcal{S}_N(\Omega,\mu) \},\$$

which coincide with the N-cyclically monotone maps, satisfy

$$\mathcal{S}_{N+1}(\Omega,\mu)^0 \subset \mathcal{S}_N(\Omega,\mu)^0,$$

for every $N \ge 1$. This can also be seen directly. Indeed, it is clear that a 2-involution is a 4-involution but not necessarily a 3-involution. On the other hand, assume that u is 3-cyclically monotone operator, then for any transformation $S: \Omega \to \Omega$, we have

$$\int_{\Omega} \langle u(x), x - Sx \rangle d\mu + \int_{\Omega} \langle u(Sx), Sx - S^2x \rangle d\mu + \int_{\Omega} \langle u(S^2x), S^2x - x \rangle d\mu \ge 0.$$

If now S is measure preserving, we have

$$\int_{\Omega} \langle u(x), x - Sx \rangle d\mu + \int_{\Omega} \langle u(x), x - Sx \rangle d\mu + \int_{\Omega} \langle u(S^2x), S^2x - x \rangle d\mu \ge 0,$$

and if $S^2 = I$, then $\int_{\Omega} \langle u(x), x - Sx \rangle d\mu \geq 0$, which means that $u \in \mathcal{S}_2(\Omega, \mu)^0$. Similarly, one can show that any (N + 1)-cyclically monotone operator belongs to $\mathcal{S}_N(\Omega, \mu)^0$. In other words, $\mathcal{S}_{N+1}(\Omega, \mu)^0 \subset \mathcal{S}_N(\Omega, \mu)^0$ for all $N \geq 2$. Note that $\mathcal{S}_1(\Omega, \mu)^0 = \{I\}^0 = L^2(\Omega, \mathbb{R}^d)$, while

$$\mathcal{S}(\Omega,\mu)^0 = \bigcap_N \mathcal{S}_N(\Omega,\mu)^0 = \{ u \in L^2(\Omega,\mathbb{R}^d), u = \nabla\phi \text{ for some convex function } \phi \text{ in } W^{1,2}(\mathbb{R}^d) \},$$

in view of classical results of Rockafellar [11] and Brenier [1].

Remark 11 In a forthcoming paper [6], the above result is extended to give a similar decomposition for any family of bounded measurable vector fields $u_1, u_2, ..., u_{N-1}$ on Ω . It is shown there that there exists a measure preserving N-involution S on Ω and an N-antisymmetric Hamiltonian H on Ω^N such that for i = 1, ..., N - 1, we have

$$u_i(x) = \nabla_{i+1} H(x, Sx, S^2x, \dots S^{N-1}x) \quad \text{for a.e. } x \in \Omega.$$

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