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The Existence of Equilibrium Flows

Alfred Galichon[†], Larry Samuelson[‡], and Lucas Vernet[§]

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Abstract Galichon, Samuelson and Vernet (2022) introduced a class of problems, *equilibrium flow problems*, that nests several classical economic models such as bipartite matching models, minimum-cost flow problems and hedonic pricing models. We establish conditions for the existence of equilibrium prices in the equilibrium flow problem, in the process generalizing Hall’s [2] theorem.

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The Existence of Equilibrium Flows

1 Introduction

Galichon, Samuelson and Vernet [1] introduced a class of problems, *equilibrium flow problems*, that nests several classical economic models such as bipartite matching models, minimum-cost flow problems and hedonic pricing models. This paper establishes conditions for the existence of equilibrium prices in the equilibrium flow problem, generalizing Hall's [2] theorem.

2 Equilibrium Flow Problem

This section duplicates the presentation of the equilibrium flow problem in Galichon, Samuelson and Vernet [1].

2.1 Formulation

Network. Consider a network $(\mathcal{Z}, \mathcal{A})$ where \mathcal{Z} is a finite set of nodes and $\mathcal{A} \subseteq \mathcal{Z} \times \mathcal{Z}$ is the set of directed arcs. If $xy \in \mathcal{A}$, we say that xy is the arc from $x \in \mathcal{Z}$ to $y \in \mathcal{Z}$, and we say that x is the starting point of the arc, while y is its end point. We assume that there is no arc in \mathcal{A} whose starting point coincides with the end point. We describe the network with an $|\mathcal{A}| \times |\mathcal{Z}|$ *arc-node incidence matrix* matrix ∇ , defined by letting, for $xy \in \mathcal{A}$ and $z \in \mathcal{Z}$

$$\nabla_{xy,z} = \mathbf{1}_{\{z=y\}} - \mathbf{1}_{\{z=x\}}.$$

We thus have $\nabla_{xy,z} = 1$ if xy is an arc ending at z , and $\nabla_{xy,z} = -1$ if xy is an arc beginning at z . Otherwise $\nabla_{xy,z} = 0$.

Prices, connection functions. Let $p \in \mathbb{R}^{\mathcal{Z}}$ be a price vector, where we interpret p_z as the price at node z . To have a concrete description, though we do not require this interpretation, one may consider a trader operating on node xy , who is able to purchase one unit of a commodity at node x , ship it along arc xy toward node y , and resell it at node y . Given the resale price at node y , there is a certain threshold value of the price at node x such that the trader is indifferent between engaging in the trade or not. This value is an increasing and continuous function of the price at node y , and can be expressed as $G_{xy}(p_y)$, where for each arc $xy \in \mathcal{A}$, the function $G_{xy} : \mathbb{R} \rightarrow \mathbb{R}$ is continuous and increasing, and called the *connection function*.¹ Hence, if $p_x > G_{xy}(p_y)$, the purchase price at node x is excessive, and the trader will not

¹This is related to the idea of a Galois connections, which explains the choice of the letter G ; see Nöldeke and Samuelson [4].

engage in the trade. On the contrary, if $p_x < G_{xy}(p_y)$, the purchase price is strictly below indifference level and positive rent can be made from the trade on the arc xy .

Our framework allows for any situation where the per-unit rent $\Pi_{xy}(p_x, p_y)$ of the trade on arc xy is a continuous and possibly nonlinear function of p_x and p_y , increasing in the resale price p_y and decreasing in the purchase price p_x . In that case, $G_{xy}(p_y)$ is implicitly defined from Π_{xy} by $G_{xy}(p_y) = \Pi_{xy}(\cdot, p_y)^{-1}(0)$, or equivalently, $\Pi_{xy}(G_{xy}(p_y), p_y) = 0$.

We refer to an equilibrium flow problem as a triple $(\mathcal{Z}, \mathcal{A}, G)$.

Exiting flow, internal flow, mass balance. Let $q \in \mathbb{R}^{\mathcal{Z}}$ with $\sum_{z \in \mathcal{Z}} q_z = 0$ attach a net flow to each node $z \in \mathcal{Z}$. If $q_z > 0$, then the net quantity $|q_z|$ must flow into node z , while $q_z < 0$ indicates that the net quantity $|q_z|$ must flow away from node z . Hence, we call q the vector of *exiting flows*. We let $\mu \in \mathbb{R}_+^{\mathcal{A}}$ be the vector of *internal flows* along arcs, so that μ_{xy} is the flow through arc xy . The feasibility condition connecting these notions is that, for any $z \in \mathcal{Z}_0$, the total internal flow that arrives at z minus the total internal flow that leaves z equals the exiting flow at z , that is

$$\sum_{x: xz \in \mathcal{A}} \mu_{xz} - \sum_{y: zy \in \mathcal{A}} \mu_{zy} = q_z,$$

which we call the *mass balance equation*, and which can be rewritten as

$$\nabla^\top \mu = q. \tag{1}$$

The interpretation of these flows will depend on the application of the equilibrium flow problem. The flows may represent quantities of commodities, volumes of traffic, assignments of objects, matches of individuals, and so on.

2.2 Equilibrium

Equilibrium flow. The triple $(q, \mu, p) \in \mathbb{R}^{\mathcal{Z}} \times \mathbb{R}_+^{\mathcal{A}} \times \mathbb{R}^{\mathcal{Z}}$ is an equilibrium outcome if it satisfies three conditions. The first condition is the conservation of the flow given by the mass balance equation (1). The second condition is that there is no positive rent on any arc, that is:

$$p_x \geq G_{xy}(p_y) \quad \forall xy \in \mathcal{A}.$$

Our third condition is that arcs with negative rents carry no flow. Hence $\mu_{xy} > 0 \implies p_x \leq G_{xy}(p_y)$, which combines with no-positive-rent requirement to yield $\mu_{xy} > 0 \implies p_x = G_{xy}(p)$. This is a complementary slackness condition, which can be written

$$\sum_{xy \in \mathcal{A}} \mu_{xy} (p_x - G_{xy}(p_y)) = 0.$$

The interpretation of these rent conditions will again depend on the application. In some cases, they will be the counterparts of zero-profit conditions in markets with entry, while in other cases they will play the role of incentive constraints.

In summary, we define:

Definition 1 (Equilibrium Flow Outcome). *The triple $(q, \mu, p) \in \mathbb{R}^{\mathcal{Z}} \times \mathbb{R}_+^{\mathcal{A}} \times \mathbb{R}^{\mathcal{Z}}$ is an equilibrium outcome when the following conditions are met:*

- (i) $\nabla^\top \mu = q$
- (ii) $p_x \geq G_{xy}(p_y) \quad \forall xy \in \mathcal{A}$
- (iii) $\sum_{xy \in \mathcal{A}} \mu_{xy} (p_x - G_{xy}(p_y)) = 0$.

The first condition implies $\sum_{z \in \mathcal{Z}} q_z = 0$. Notice that if p satisfies condition (ii), then setting $q = 0$ and $\mu = 0$ ensures that the remaining conditions are satisfied. Indeed, if (q, μ, p) is a equilibrium flow outcome, then so is $(\lambda q, \lambda \mu, p)$ for any nonnegative scalar λ . Hence, there will either be no equilibrium flow outcome (if there is no p satisfying condition (ii)) or there will be multiple equilibrium flows outcomes.

3 Existence of Equilibrium

We fix a vector of exit flows q (with $\sum_{z \in \mathcal{Z}} q_z = 0$) and ask whether there exists a price vector p and flow μ such that (q, μ, p) is an equilibrium of the equilibrium flow problem.

3.1 Feasibility Conditions

For a subset B of \mathcal{Z} , an arc xy is said to be outward if $x \in B$ and $y \notin B$. A subset B of \mathcal{Z} is called retaining if there is no arc outward of B . Hence, subset B is retaining if and only if

$$\nabla \mathbf{1}_B \geq 0.$$

Our existence result obviously requires some feasibility condition. In the extreme, one cannot find an equilibrium flow in a network with no arcs (and nontrivial q). We state the feasibility condition in terms of retaining sets.

Assumption 1. *If B is a retaining set, then $q(B) = \sum_{z \in B} q_z \geq 0$.*

Assumption 1 serves its intended purpose of ensuring it is at least possible to construct a flow that transports the goods in the network from their origins to their destinations:

Lemma 1. *Let $q \in \mathbb{R}^{\mathcal{Z}}$ be such that $\sum_{z \in \mathcal{Z}} q_z = 0$. Then the following statements are equivalent.*

- [1.1] *There exists $\mu \in \mathbb{R}_+^{\mathcal{A}}$ such that $q = \nabla^\top \mu$.*
- [1.2] *For each B retaining subset of \mathcal{Z} , one has $q(B) \geq 0$.*

Proof That [1.1] implies [1.2] is straightforward: If there is no arc from a node in B to a node in $\mathcal{Z} \setminus B$, then mass can only enter into B , and so we must have $q(B) \geq 0$.

To show the converse, we exploit Hoffman's [3] circulation theorem. For any subset $B \subset \mathcal{Z}$, let $\mathcal{O}(B) = \{xy \in \mathcal{A} : x \in B, y \notin B\}$, and $\mathcal{I}(B) = \{xy \in \mathcal{A} : x \notin B, y \in B\}$ be respectively the set of outward and inward arcs of B . Hoffman's theorem states that, given $q \in \mathbb{R}^{\mathcal{Z}}$ with $\sum_{z \in \mathcal{Z}} q_z = 0$ and $\underline{\mu}$ and $\bar{\mu}$ in $\mathbb{R}_+^{\mathcal{A}}$ there exists $\mu \in \mathbb{R}_+^{\mathcal{A}}$ such that

$$\nabla^\top \mu = q \quad \text{and} \quad \underline{\mu} \leq \mu \leq \bar{\mu}$$

if and only if for all subsets B of \mathcal{Z} , one has

$$\sum_{z \in B} q_z \leq \sum_{a \in \mathcal{I}(B)} \bar{\mu}_a - \sum_{a \in \mathcal{O}(B)} \underline{\mu}_a.$$

This result is usually stated for $q = 0$, but the adaptation to nonzero q straightforward. With this result in hand, let $\bar{\mu}_a = +\infty$ and $\underline{\mu}_a = 0$, so that we can rewrite Hoffman's condition as the requirement that for all sets \tilde{B} that have no inbound links,

$$q(\tilde{B}) \leq 0.$$

We then argue that this condition is equivalent to the second condition in Lemma 1. Call a set with no inbound links *repelling*. The result then follows from noting that the set $B \subset \mathcal{Z}$ is retaining if and only if B^c is repelling, and for any set B ,

$$q(B) + q(B^c) = 0.$$

■

Remark 1 (Hall's marriage theorem). Lemma 1 implies Hall's [2] marriage theorem. To see this, assume we are in the bipartite case to which Hall's lemma applies. Hence, $\mathcal{Z} = \mathcal{X} \cup \mathcal{Y}$ and $\mathcal{A} \subseteq \mathcal{X} \times \mathcal{Y}$.

From Lemma 1, we then have that q is attainable if and only if for all retaining sets B , one has $q(B) \geq 0$. That is, for all retaining sets B , one has

$$q(B \cap \mathcal{X}^c) + q(B \cap \mathcal{X}) \geq 0.$$

Therefore for all subsets B of $\mathcal{Z} \setminus \mathcal{X}$ and for all B' in \mathcal{X} , then

$$[B \subset \mathcal{Z} \setminus \mathcal{X}, B' \subset \mathcal{X}, B \cup B' \text{ retaining}] \implies [q(B) \geq -q(B')]. \quad (2)$$

Now let $B' \subset \mathcal{X}$ and let B be the set of nodes z in \mathcal{Y} with the property that there is an arc from a node in B to z . Then by construction $B \cup B'$ is retaining, and so (2) gives

$$q(B) \geq -q(B'),$$

which is Hall's marriage theorem. ■

We make an additional, technical feasibility assumption.

Assumption 2. *For each $z \in \mathcal{Z}$, either $q_z > 0$ or there exists a path from z to a node $y \in \mathcal{Z}$ with $q_y > 0$.*

To see why we refer to this as a technical assumption, notice that it is automatically satisfied if $q_z > 0$, and is implied by Assumption 1 if $q_z < 0$. However, Assumption 1 is compatible with the existence of a node z with $q_z = 0$ that fails Assumption 2. In this case, it is impossible for an equilibrium to exhibit flow through node z , and we can without loss of generality eliminate node z from the network. Assumption 2 thus ensures that there are no obviously irrelevant nodes in the network. We could accommodate such nodes, but then would require another step in our equilibrium construction, to attach prices to such nodes.

3.2 A Profitability Condition

Assumption 1 ensures that there exists a flow capable of moving goods from their sources to their destinations. However, in equilibrium the flow must make use of only zero-rent arcs and there must be no positive-rent arcs. We accordingly require a condition on the profitability of arcs.

For x and y in \mathcal{Z} , we introduce the reduced connection $\tilde{G}_{xy}(p_y)$ as

$$\tilde{G}_{xy}(p_y) = \sup_{\substack{x_0=x, x_1, x_2, \dots, x_{k+1}=y \\ x_\ell x_{\ell+1} \in \mathcal{A}}} G_{xx_1} \circ G_{x_1x_2} \circ \dots \circ G_{x_k y}(p_y)$$

which can either be finite or $+\infty$ if this quantity is unbounded. We shall take the convention that $\tilde{G}_{xy}(p_y) = -\infty$ if there is no directed path between x and y .

We say that the collection of nodes $(x_0, x_1, \dots, x_{k+1})$ is a loop if it contains $k+1$ distinct nodes and $x_0 = x_{k+1} =: x$. We assume:

Assumption 3. *If $(x_0, x_1, \dots, x_{k+1})$ is a loop, then $p > G_{xx_1} \circ G_{x_1x_2} \circ \dots \circ G_{x_k x}(p)$ for all p .*

Assumption 3 ensures there is no way to achieve positive rents by moving flow through a loop, with no net change in the allocation. If such a loop existed, continual movement along this loop would constitute a money pump, giving rise to infinite rents. Equivalently, if Assumption 3 fails, then it may be impossible to assign prices to nodes in such a way as to ensure the absence of positive-rent arcs.

3.3 The Existence Result

Lemma 1 ensures that it is possible to transport the required mass from sources to targets. Assumption 3 ensures that it is possible to attach prices to nodes so that there are no positive-rent arcs. In equilibrium, we require some coordination between

these two constructions, in that equilibrium flow must transport the required mass from sources to targets using only zero-rent arcs. It would accordingly be no surprise if additional conditions were required to ensure the existence of an equilibrium flow. However, these assumptions suffice:

Theorem 1. *Let Assumptions 1-3 hold. Then there exists an equilibrium flow.*

The proof of this result, occupying Sections (3.4)–(3.6), associates the equilibrium flow problem with an associated bipartite matching problem, and then exploits existence results for the bipartite matching problem. This association may be useful for other purposes.

3.4 Equilibrium Flows and Bipartite Solutions

Given an equilibrium flow problem, define the source nodes as $\mathcal{X} = \{x \in \mathcal{Z} : q_x < 0\}$ and the target nodes as $\mathcal{Y} = \{y \in \mathcal{Z} : q_y > 0\}$. We now associate with the equilibrium flow problem $(\mathcal{Z}, \mathcal{A}, G)$ the bipartite imperfectly transferable utility matching problem $(\mathcal{X}, \mathcal{Y}, \tilde{G})$.

Lemma 2. *Fix a profile of exit flows q with $\sum_{z \in \mathcal{Z}} q_z = 0$. Then there exists an equilibrium (q, μ, p) for the equilibrium flow problem $(\mathcal{Z}, \mathcal{A}, G)$ if and only if there exists an equilibrium $(q, \tilde{\mu}, \tilde{p})$ for the associated bipartite problem $(\mathcal{X}, \mathcal{Y}, \tilde{G})$ such that p and \tilde{p} agree on \mathcal{X} and \mathcal{Y} .*

Proof. First, let (q, μ, p) be a solution to the equilibrium flow problem. We derive a corresponding bipartite solution.

First, we have for $x \in \mathcal{X}$ and $y \in \mathcal{Y}$ that

$$p_x \geq \tilde{G}_{xy}(p_y).$$

Indeed, for any path $x = x_0, x_1, x_2, \dots, x_{k+1} = y$ from x to y , we have (from the no-positive-rent equilibrium condition) $p_{x_k} \geq G_{x_k x_{k+1}}(p_{x_{k+1}})$ and thus

$$p_x \geq G_{xx_1} \circ G_{x_1 x_2} \circ \dots \circ G_{x_k y}(p_y).$$

Taking the maximum over paths from x to y , we have $p_x \geq \tilde{G}_{xy}(p_y)$.

By the flow decomposition theorem, one can write

$$\mu = \sum_{p \in \Pi} \mu^p + \sum_{l \in L} \mu^l$$

where μ^p is the flow associated with path p , and μ^l is the flow associated with loop l , Π is the set of paths, and L is the set of loops. Clearly $\mu_l = 0$ for any loop l , otherwise the assumption of absence of profitable loop would be violated.

Consider Π_{xy} , which is the set of paths beginning at x and ending at y . Let $\tilde{\mu}_{xy} = \sum_{p \in \Pi_{xy}} \mu^p$. It is straightforward that for all $x \in \mathcal{X}$ and $y \in \mathcal{Y}$ we have

$$\begin{aligned} \sum_{x \in \mathcal{Y}} \tilde{\mu}_{xy} &= n_x \\ \sum_{x \in \mathcal{X}} \tilde{\mu}_{xy} &= m_y. \end{aligned}$$

In addition, we have that $\tilde{\mu}_{xy} > 0$ implies that there is a path $(x_0, x_1, x_2, \dots, x_{k+1})$ from $x (= x_0)$ to $y (= x_{k+1})$ along which the flow is strictly positive. Thus, along this path, $p_{x_\ell} = G_{x_\ell x_{\ell+1}}(p_{x_{\ell+1}})$ and thus

$$p_x = G_{xx_1} \circ G_{x_1x_2} \circ \dots \circ G_{x_ky}(p_y);$$

but as $p_x \geq \tilde{G}_{xy}(p_y) \geq G_{xx_1} \circ G_{x_1x_2} \circ \dots \circ G_{x_ky}(p_y)$, it follows that equality holds everywhere and thus

$$p_x = \tilde{G}_{xy}(p_y).$$

Therefore we have the an equilibrium $(q, \tilde{\mu}, \tilde{p})$ for the bipartite problem, i.e., satisfying:

$$\begin{aligned} \sum_{x \in \mathcal{Y}} \tilde{\mu}_{xy} &= n_x \\ \sum_{x \in \mathcal{X}} \tilde{\mu}_{xy} &= m_y \\ \tilde{p}_x &\geq \tilde{G}_{xy}(\tilde{p}_y) \\ \tilde{\mu}_{xy} > 0 &\implies \tilde{p}_x = \tilde{G}_{xy}(\tilde{p}_y) \end{aligned} \quad (3)$$

For the reverse direction of the proof, suppose $(q, \tilde{\mu}, \tilde{p})$ is an equilibrium of the bipartite solution (p_x^*, p_y^*) , and hence satisfies (3). To find an associated equilibrium (q, μ, p) of the equilibrium flow problem, we retain the specification of q , let μ be any flow consistent with $\tilde{\mu}$, and define an iterative procedure that generates the prices p . For the initial step, we let

$$p_z^0 = \begin{cases} \tilde{p}_z & \text{if } z \in \mathcal{X} \cup \mathcal{Y} \\ -\infty & \text{otherwise} \end{cases},$$

with the induction step given by

$$p_x^{t+1} = \max \left\{ p_x^t, \max_{y:xy \in \mathcal{A}} \{ G_{xy}(p_y^t) \} \right\}.$$

We then complete the argument with the the following lemma:

Lemma 3. *for t large enough (but finite), (q, μ, p^t) an equilibrium of the equilibrium flow problem.*

Proof. We establish this result in a series of steps:

1. After a finite number of steps, $p_z^t > -\infty$ for all z .

To see this, let $d(x \rightsquigarrow y)$ be the length of the shortest path from x to y . Then we have $p_x^t = \max_{y \in \mathcal{Y}} \max_{x \rightsquigarrow y: l(x \rightsquigarrow y) \leq t} G_{x \rightsquigarrow y}(p_y)$. Hence, if there is a directed path of length at most k from z to \mathcal{Y} , then the price of z will become finite after in at most k steps. As a result, all prices will be updated after

$$\max_z \min_{y \in \mathcal{Y}} d(z, y),$$

and so after a finite number of step, $p_z^t > -\infty$ for all z .

2. The price of a node $y \in \mathcal{Y}$ is never updated by the algorithm.

Assume that one updates $y \in \mathcal{Y}$ at some step. Then there is a chain $y \rightsquigarrow y'$ from y to some $y' \in \mathcal{Y}$ with $p_y < G_{y \rightsquigarrow y'}(p_{y'})$. Let $x \in \mathcal{X}$ be an element of \mathcal{X} such that $\pi_{xy} > 0$. One has $p_x = \tilde{G}_{xy}(p_y)$, thus $p_x < \tilde{G}_{xy} \circ G_{y \rightsquigarrow y'}(p_{y'}) = G_{x \rightsquigarrow y'}(p_{y'}) \leq \tilde{G}_{xy'}(p_{y'})$, a contradiction.

3. There exists a T such that for all $t > T$ the algorithm is stationary .

We construct an updating digraph as follows: at $t = 0$, the graph has no edge. At $t > 0$, if $p_x^{t+1} < \max_{y: xy \in \mathcal{A}} \{G_{xy}(p_y^t)\}$, then we pick up one y that attains the maximum (resolving ties arbitrarily) and we add a directed arc from x to y . It is a direct consequence of Assumption 3 that this digraph is a forest. Because there are only a finite number of possible forests, the updating process must stop within finite many steps.

4. For all $x \in X$, $p_x^T = p_x^*$.

By contradiction, if there exists a x such that $p_x^T \neq p_x^*$ when the algorithm is stationary then:

- If $p_x^T > p_x^*$, then there exists a path $x \rightsquigarrow y$ such that $p_x^T = G_{x \rightsquigarrow y}(p_y) > p_x^* = \max_{y' \in \mathcal{Y}} \tilde{G}_{xy'}(p_{y'}) > G_{x \rightsquigarrow y}(p_y)$, contradiction.
- If $p_x^T < p_x^*$, then there is a $y \in \mathcal{Y}$ and a path $x \rightsquigarrow y$ such that $p_x^* = G_{x \rightsquigarrow y}(p_y)$. Moving along path $x \rightsquigarrow y$, take the last z such that $p_z^T \neq \tilde{G}_{zy}(p_y)$, and z' be its successor. One has by definition $p_z^T < \tilde{G}_{zy}(p_y) = G_{zz'}(\tilde{G}_{z'y}(p_y)) = G_{zz'}(p_{z'}^T)$, which contradicts the fact that the algorithm has reached stationarity.

This completes the proof of Lemma 2. ■

3.5 Bipartite Existence Result

Lemma 4. *If the bipartite problem satisfies Hall's condition, then there exists an equilibrium flow for the bipartite network.*

Proof. Let n_x and m_y be two vectors on \mathcal{X} and \mathcal{Y} which sum to the same amount. Our interpretation is that n_x identifies the mass at each node $x \in X$ that must be transported away from x , and m_y identifies the mass at each node $y \in Y$ that must be transported to y . The requirement that these vectors have the same sum is equivalent to the condition $\sum_{z \in Z} q_z = 0$ in the equilibrium flow problem.

Consider $\mathcal{A} \subseteq \mathcal{X} \times \mathcal{Y}$, and assume Hall's conditions are satisfied: for all $K \subseteq \mathcal{X}$,

$$\sum_{x \in K} n_x \geq \sum_{y \in \mathcal{Y}} m_y \mathbf{1}_{\{\forall x: xy \in \mathcal{A}, x \in K\}}.$$

This condition would be automatically satisfied if the network is fully connected, i.e., if $\mathcal{A} = \mathcal{X} \times \mathcal{Y}$, but we allow the network to be incomplete.

The strategy is to exploit existence results for complete bipartite networks. Toward this end, we fix an integer $n > 0$, we extend the set of arcs \mathcal{A} to the set $\mathcal{X} \times \mathcal{Y}$ by letting, for each $x \in (\mathcal{X} \times \mathcal{Y}) \setminus \mathcal{A}$

$$G_{xy}(p_y) = p_y - n.$$

We now consider a matching on the complete graph. If this matching directs flow along the arc $x \in (\mathcal{X} \times \mathcal{Y}) \setminus \mathcal{A}$, then we must have $p_x = p_y - n$. We then argue that for sufficiently large n , flow along any such arc is so unprofitable that the equilibrium will not exhibit such flow. This will ensure that the equilibrium is also an equilibrium of the problem with the set of arcs \mathcal{A} .

Hence, let (μ_{xy}^E, p_x, p_y) be such that

- (i) $\sum_y \mu_{xy}^E = n_x$ and $\sum_x \mu_{xy}^E = m_y$,
- (ii) $p_x \geq G_{xy}(p_y)$ for all $x \in \mathcal{X}, y \in \mathcal{Y}$
- (iii) $\mu_{xy}^E > 0$ implies $p_x = G_{xy}(p_y)$ if $xy \in \mathcal{A}$, and $p_x = p_y - n$ otherwise.
- (iv) $p_0 = 0$ for some ground node $0 \in \mathcal{X} \cup \mathcal{Y}$

The existence of this matching follows from Proposition 6 of Nöldeke and Samuelson. The key to applying this proposition is to note that the function $G_{xy}(p_y)$ is increasing, continuous, and as p_y varies, sweeps out the entire real line.

Consider a directed graph on $\mathcal{Z} = \mathcal{X} \cup \mathcal{Y}$ whose set of arcs is

$$\mathcal{A}^* = \{xy \in \mathcal{A}\} \cup \{yx : x \in \mathcal{X}, y \in \mathcal{Y}, \mu_{xy}^E > 0\}$$

We show the following intermediate result:

Lemma 5. *Assume $x^*y^* \notin \mathcal{A}$ and $\mu_{x^*y^*}^E > 0$. There exists no partition \mathcal{Z} into A and B in such a way that $y^* \in A$, $x^* \in B$ and there are no arcs of \mathcal{A}^* from B to A .*

Proof. We show the lemma by contradiction. Suppose such partition existed, and denote $A^{\mathcal{X}} = A \cap \mathcal{X}$, $A^{\mathcal{Y}} = A \cap \mathcal{Y}$, and $B^{\mathcal{X}}$ and $B^{\mathcal{Y}}$ in a similar fashion.

Because there are no arcs from $B^{\mathcal{X}}$ to $A^{\mathcal{Y}}$, Hall's conditions imply that $n_x(A^{\mathcal{X}}) \geq m_y(A^{\mathcal{Y}})$.

Now, because there are no arcs from $B^{\mathcal{Y}}$ to $A^{\mathcal{X}}$, the existence of μ^E implies that $n_x(B^{\mathcal{X}}) \geq m_y(B^{\mathcal{Y}})$.

Summing the previous two inequalities yields $n_x(\mathcal{X}) \geq m_y(\mathcal{Y})$, but as this holds as an equality, we get an equality in the two previous inequalities. Thus $n_x(A^{\mathcal{X}}) = m_y(A^{\mathcal{Y}})$ and $n_x(B^{\mathcal{X}}) = m_y(B^{\mathcal{Y}})$.

Now $n_x(A^{\mathcal{X}}) = \sum_{x \in A^{\mathcal{X}}} \sum_{y \in \mathcal{Y}} \mu_{xy}^E$, but for $x \in A^{\mathcal{X}}$ and $y \in B^{\mathcal{Y}}$, $\mu_{xy}^E = 0$ otherwise there would be an arc of \mathcal{A}^* from B to A . Hence

$$n_x(A^{\mathcal{X}}) = \sum_{x \in A^{\mathcal{X}}} \sum_{y \in A^{\mathcal{Y}}} \mu_{xy}^E$$

Comparing with

$$n_Y(A^{\mathcal{Y}}) = \sum_{x \in \mathcal{X}} \sum_{y \in A^{\mathcal{Y}}} \mu_{xy}^E$$

yields a difference of

$$\sum_{x \in B^{\mathcal{X}}} \sum_{y \in A^{\mathcal{Y}}} \mu_{xy}^E,$$

and hence for all $x \in B^{\mathcal{X}}$ and $y \in A^{\mathcal{Y}}$, $\mu_{xy}^E = 0$, which contradicts $x^* \in B^{\mathcal{X}}$, $y^* \in A^{\mathcal{Y}}$ and $\mu_{x^*y^*}^E > 0$. This contradiction proves the claim. \blacksquare

The proof of Lemma 4 is then completed by the following lemma.

Lemma 6. *For n large enough, $\mu_{x^*y^*}^E > 0$ implies $x^*y^* \in \mathcal{A}$.*

Proof. We prove the result in the following manner. Start by taking $A = \{y^*\}$ and $B = \mathcal{Z} \setminus \{y^*\}$. Then there must be an arc from B to A . Call z the origin point of that arc, and repeat with $A = \{y^*, z\}$ and $B = \mathcal{Z} \setminus \{y^*, z\}$, and so on, until x^* is chosen. We end up with a path from x^* to y^* . Calling $z_0 = y^*, z_1, \dots, z_K = x^*$ that path, we have that $p_{y^*} \leq G_{y^*z_1} \circ \dots \circ G_{z_{K-1}z_K}(p_{x^*})$ where for $yx \in \mathcal{A}^* \setminus \mathcal{A}$, one has defined $G_{yx} = G_{xy}^{-1}$. However, $\mu_{x^*y^*}^E > 0$ would imply $p_{x^*} = G_{x^*y^*}(p_{y^*}) = p_{y^*} - n$. Hence, we have

$$p_{y^*} \leq G_{y^*z_1} \circ \dots \circ G_{z_{K-1}z_K}(p_{x^*}) \tag{4}$$

$$p_{y^*} = p_{x^*} + n. \tag{5}$$

Equation (5) shows that as n grows, $p_{y^*} - p_{x^*}$ diverges. We show that this gives a contradiction, establishing the theorem. Write $p_{y^*} - p_{x^*}$ as

$$p_{y^*} - p_{x^*} = p_{y^*} - p_{z_1} \quad (1)$$

$$+ p_{z_1} - p_{z_2} \quad (2)$$

$$+ p_{z_2} - p_{z_3} \quad (3)$$

$$+ p_{z_3} - p_{z_4} \quad (4)$$

$$+ p_{z_4} - p_{z_5} \quad (5)$$

$$+ p_{z_5} - p_{z_6} \quad (6)$$

\vdots

$$+ p_{z_K} - p_{x^*} \quad (\cdot).$$

The terms with odd numbers correspond to arcs from X to Y , and are contained in \mathcal{A} . (The final \cdot is an odd-numbered term.) The terms with even numbers are arcs from Y to X , contained in $\mathcal{A}^* \setminus \mathcal{A}$. Suppose first that as n grows, p_{y^*} approaches a limit. This imposes a lower bound on p_{z_1} (since $z_1 y^* \in \mathcal{A}$ and hence we need nonpositive rent on this arc). Since flow moves along arc $z_1 z_2$, this in turn ensures either that there is a lower bound on p_{z_2} (if the arc $z_1 z_2 \in \mathcal{A}$) or that p_{z_2} diverges to $+\infty$ (if $z_1 z_2 \notin \mathcal{A}$). Continuing in this fashion, it cannot be the case that p_{x^*} diverges to $-\infty$, a contradiction. A similar argument can be constructed, beginning from the assumption that p_{x^*} approaches a limit as n grows large, and yet a similar construction ensures that it cannot be the case that $p_{y^*} \rightarrow +\infty$ and $p_{x^*} \rightarrow -\infty$.

It remains to preclude the possibilities that p_{x^*} and p_{y^*} both approach $+\infty$ or both approach $-\infty$, which is done in Appendix A. this ensures we have an equilibrium involving only arcs in \mathcal{A} , which is to say that we have an equilibrium flow. \blacksquare

This completes the proof of Lemma 4. \blacksquare

3.6 Closing the Ring

The proof of Theorem 1 is then completed by the following:

Lemma 7. *The network $(\mathcal{Z}, \mathcal{A})$ and exit flow satisfy*

$$q(B) \geq 0$$

for all retaining B if and only if the associated bipartite matching problem $(\mathcal{X}, \mathcal{Y})$ together with the exit flow q satisfies Hall's marriage condition.

Proof. First, suppose $q(B) \geq 0$ for all retaining sets. Suppose $\tilde{X} \cup \tilde{Y}$ is a subset of $X \times Y$ for which, in the bipartite matching problem, there are no arcs from nodes in \tilde{X} to nodes outside \tilde{Y} . In the network flow problem, define a sequence of sets by

letting $Z_1 = \tilde{X} \cup \tilde{Y}$, letting Z_2 be the union of Z_1 and any node that is the endpoint of an arc whose origin lies in Z_1 ; letting Z_3 be the union of Z_1 and any node that is the endpoint of an arc whose origin lies in Z_1 , and so on. This sequence terminates (since the set \mathcal{Z} of nodes is finite) in a set Z^* that is retaining (otherwise the process would not terminate) and hence satisfies $q(Z) \geq 0$. Moreover, Z^* contains no node z for which $q(z) > 0$ that is not contained in \tilde{Y} (since otherwise there would be a link in the bipartite matching problem from some node in \tilde{X} to a node outside \tilde{Y} , a contradiction). Then we have

$$0 \leq q(Z^*) \leq q(\tilde{X} \cup \tilde{Y}),$$

giving Hall's condition.

Second, for the other direction, let \tilde{Z} be a retaining set. Then

$$q(\tilde{Z}) = q((X \cap \tilde{Z}) \cup (Y \cap \tilde{Z}))$$

Because Z is retaining, in the bipartite problem there are no links from $X \cap \tilde{Z}$ to $Y \cap \tilde{Z}$. Hence, Hall's condition gives $q((X \cap \tilde{Z}) \cup (Y \cap \tilde{Z}))$, establishing the needed result. ■

A Appendix: Completion of Proof of Lemma 6

We present the argument for the case in which both approach $+\infty$, with the other case being analogous. If p_{x^*} and p_{y^*} both approach $+\infty$, then we can divide \mathcal{X} into disjoint sets $\underline{\mathcal{X}}$ and $\overline{\mathcal{X}}$ and can divide \mathcal{Y} into disjoint sets $\underline{\mathcal{Y}}$ and $\overline{\mathcal{Y}}$ such that the prices in $\overline{\mathcal{X}}$ and $\overline{\mathcal{Y}}$ diverge and the prices in $\underline{\mathcal{X}}$ and $\underline{\mathcal{Y}}$ do not diverge. The sets $\overline{\mathcal{X}}$ and $\overline{\mathcal{Y}}$ are nonempty, because they contain x^* and y^* . The set $\underline{\mathcal{X}}$ is nonempty because it contains the ground node p_0 . There must be no arcs in \mathcal{A} from $\underline{\mathcal{X}}$ to $\overline{\mathcal{Y}}$ (since otherwise such an arc would generate positive rent, a contradiction). There must exist no flow from nodes in $\overline{\mathcal{X}}$ to nodes in $\underline{\mathcal{Y}}$ (since these arcs earn negative rent). Any flow from $\underline{\mathcal{X}}$ to $\underline{\mathcal{Y}}$ must occur along arcs in \mathcal{A} , since otherwise the arc must earn negative rent. Hall's condition must then hold for the system whose nodes are $\underline{\mathcal{X}}$ and $\underline{\mathcal{Y}}$, and then must separately hold the system whose nodes are $\overline{\mathcal{X}}$ and $\overline{\mathcal{Y}}$.

Intuitively, we now repeat the previous existence argument separately for each of these systems, with one ground \underline{p}_0 for the system whose nodes are $\underline{\mathcal{X}}$ and $\underline{\mathcal{Y}}$ and one ground node \overline{p}_0 for the system whose nodes are $\overline{\mathcal{X}}$ and $\overline{\mathcal{Y}}$. This gives us an equilibrium for each system separately. We cannot be sure that we have an equilibrium of the combines systems, since there may be arcs in \mathcal{A} from $\overline{\mathcal{X}}$ to $\underline{\mathcal{Y}}$. However, if we set \underline{p}_0 sufficiently low and \overline{p}_0 sufficiently high, these arcs will carry no flow, and we will indeed have an equilibrium.

To make this argument precise we note that given any sets \mathcal{X} and \mathcal{Y} satisfying Hall's condition, we can partition these sets into $((\mathcal{X}_1, \mathcal{Y}_1), (\mathcal{X}_2, \mathcal{Y}_2), \dots, (\mathcal{X}_n, \mathcal{Y}_n))$ with the property that Hall's condition holds separately for each pair $(\mathcal{X}_k, \mathcal{Y}_k)$, and

the are no arcs in \mathcal{A} from any \mathcal{X}_k to \mathcal{Y}_j for $j > k$. Now we start at the bottom and use our basic argument to fix a price at a ground node $p_0(1)$ in \mathcal{X}_1 and find an equilibrium of the system $(\mathcal{X}_1, \mathcal{Y}_1)$. In particular, we cannot have prices diverge when we get to the last step of this argument, since otherwise we could have decomposed $(\mathcal{X}_1, \mathcal{Y}_1)$ further. Next, we fix a ground node $p_0(2)$ in \mathcal{X}_2 and repeat the same construction in $(\mathcal{X}_2, \mathcal{Y}_2)$. This gives us an equilibrium for $(\mathcal{X}_2, \mathcal{Y}_2)$, and moreover, by making $p_0(2)$ sufficiently large, we can ensure that there is no positive rent on any arc in \mathcal{A} from a node in \mathcal{X}_2 to a node in \mathcal{Y}_1 (recall that by construction there are no arcs from \mathcal{X}_1 to \mathcal{Y}_2), ensuring that together, we have an equilibrium for the system consisting of $\mathcal{X}_1 \cup \mathcal{X}_2$ and $\mathcal{Y}_1 \cup \mathcal{Y}_2$.² We then continue in this fashion.

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²We are using here the property that as we increase the price $p_0(2)$, all the equilibrium prices in the system $(\mathcal{X}_2, \mathcal{Y}_2)$ increase. If this was not the case, we could further decompose $(\mathcal{X}_2, \mathcal{Y}_2)$, which by assumption we cannot.